Sensor for Breast Imaging Device

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Client- Professor Hagness

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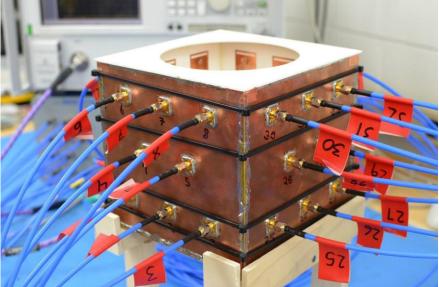


Figure 1: Picture of 3D imaging device courtesy of Owen Mays.



Outline

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- Problem Statement
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Background

- 1 in 8 women develop breast cancer
- 30% of cancer in women
- Initial screening
 - o Mammogram
 - \circ X-ray





Figure 2: Example of x-ray device used in a mammography [4].



Background

- Mammography gold standard
- Underserved population
 - Higher risk
 - High breast density
 - Harder to screen
- MRI has 50% false-positive

References: [6]



Background

3D microwave imaging device

- Fraction of cost of MRI
- Ease of use
- Accessibility
- Low health risk
- Conductivity and permittivity of tissue
 - Contrast
 - Biocompatible contrast agents

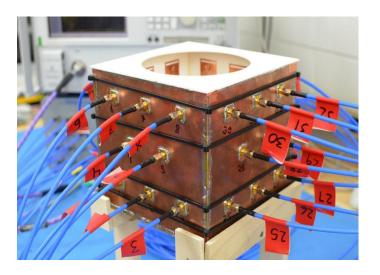


Figure 1: Picture of 3D imaging device courtesy of Owen Mays.

References: [6]



Motivation

- Filling/draining currently performed by human
 - Requires significant effort
 - Can't tell how much liquid needed
 - Large margin of error, frequent spills
- Client needs pump with sensor
 - Monitors liquid level, stops at top
 - Adjusts volume filled with breast size



Problem Statement

- Sensor / Pump system
- Automated
- Fill / Drain
- Portable
- Fill time < 5 Min



Client Requirements

- No metal inside box
- Two holes maximum
 1cm or smaller
- Not reliant on manual operator
- No size constraint
 - Wheeled into room
 - Fit under MR bed
- \$600 budget



Figure 3: Picture of cart that patient is placed on for the breast imaging procedure. Red circle denotes the prospective location of the device. Picture courtesy of Owen Mays.



Design 1: Piezo-Resonant Sensor

- Non-intrusive
- Acoustic impedance mismatch
- Plastics compatible
- USB interface



Figure 4: Image of Piezo-resonant sensor. [7]



Design 2: FSR Sensor

- Microcontroller
- Minimally intrusive
- Circuits
- Placement of sensor



Figure 5: Various sizes of FSR Sensors. [5]



Design 3: Kill-Switch

- No microcontroller
- Invasive
- Automatic shutoff

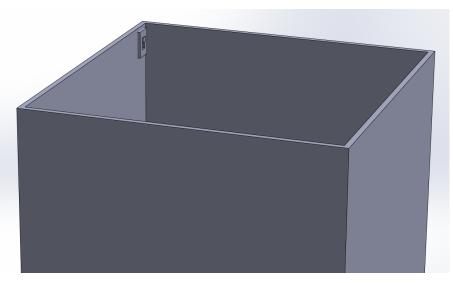


Figure 6: Proposed implementation of kill-switch design.

Buoyant ball



Design Evaluation Matrix

Criteria	Weight	Piezo- Resonant	FSR	Kill-Switch
Invasiveness	30	30	10	10
Reliability	30	25	20	15
Feasibility	20	15	10	17
Compatibility	15	10	5	15
Removability	5	5	0	0
Total	100	<u>85</u>	45	57



Future Work

- Construct model box
- Research new non-invasive sensor
- Order sensor
- Perform sensor testing
- Incorporate pump in prototype, retest



References

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Questions?