

Abstract

Ms. Carol Rohl is a hemiplegic woman who suffered a thalamic bleed in 2004. Our team has been approached to assist in her rehabilitation. Currently, she does not know when her stance is balanced due to a lack of sensory feedback on the left side of her body. She would like a portable weight distribution monitoring system that she can use to train herself to recognize an even weight distribution.

Background

Strokes and Hemiplegia

•3.5 million stroke survivors in U.S., 600,000 new cases each year

•\$30 billion in healthcare costs

•Brain tissue damage reduces neural traffic, impairment of motor neuron activation •Causes loss of motor, sensory functions in hemiplegic area

Balance Improvement

•Rehabilitation exercises to increase weight hemiplegic limb supports

•Force platforms used, but only clinically

Client Specifications/

Design Requirements

- •Portable with compact storage
- •Eye level visual feedback with simple user interface
- •Accommodate shoulder width stance
- •Withstand frequent use
- •Around notebook size with unfolded height less than 1 in.
- •Lightweight
- •Pick up and carry device with one hand

Acknowledgements

Dr. Willis Tompkins Carol Rohl Dr. Bonnie Tompkins Dr. Amit Nimunkar

Dr.. Tom Yen Sabic Innovative Plastics Dr. Michael Matysik

WEIGHT DISTRIBUTION **MONITORING SYSTEM** Katherine Hildebrand, Scott Mawer, Russell Little, John Diaz de Leon III

Advisor - Willis Tompkins, PhD Clients - Carol Rohl, Bonnie Tompkins Department of Biomedical Engineering UW Madison

Final Design



•Hinged platform folds in half •FSRs between sheets of polycarbonate •Arduino microcontroller calculates voltage difference •Row of LEDs to show degree of imbalance

Testing



100 lb. forces



Arduino Microprocesso FlexiForce FSR (2) Project Enclosures (2)

> Assorted LEDs Polycarbonate Sheet Hardware, Circuit Components

•No set budget, but completed prototype for less than \$150

1" high, 17 1/4" wide, 13 7/8" long Weighs less than 6 lb. LED feedback box at eye level Successfully satisfied client's requirements

- of foot placement •Expand calibration range
- •Accommodate variety of stances
- •In-depth feedback option
- •Bluetooth connectivity

- 312.
- Archives of Neurology Volume 59, Sep. 2002: 1453-1457.
- Cochrane Library 2009.
- 181.
- balance." Gait and Posture 2010: 307-310.
- Posture 2005: 48-58.

- •Range of weights from 12.5 to
- •Linear fit of voltage-force plots for both FSRs
- •Apply to code for normalizing
- •Subject testing for distribution boundaries



Budget

or	\$24.95
	\$76.05
)	\$8.98
	фо. О О
	\$8.38
,	\$0
	\$31

Results

Future Work

•Refine force sensing system to minimize importance

References

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