

Non-metallic Intraocular Foreign Body Extraction Device

Abstract

Intraocular foreign bodies (IOFB) account for nearly 40% of open-globe ocular traumas. When they penetrate the eye, they are subject to surgical removal. However, removal is complicated when the IOFB are round, smooth, and non-metallic, such as air soft pellets. Currently, no surgical instrument exists specifically to remove these IOFB. An instrument, with a locking grasp mechanism was designed to remove air-soft pellets six millimeters in diameter. A retractable claw prototype device was fabricated and tested for user comfort and reliability.

Background

Retina _____

Optic Nerve

Central retinal v

Fovea centralis

Intraocular Foreign Bodies (IOFB)

- Penetrate ocular tissue
- Retained inside eye
- Range in size and composition variably
- Subject to surgical removal [1]

Human Eye Anatomy

- IOFB penetrates:
 - Cornea (65%)
 - Sclera (25%)
- IOFB retained by:
 - Vitreous Body (61%) Central retinal a.
 - Gel-like fluid
 - Pressurizes eye
 - Anterior Chamber (15%)
 - Retina (14%)
 - Optic nerves
 - Delicate [3]

Inferior rectus Figure 1: Anatomy of Human Eye.[2]

Vitreous Body

IOFB Removal: Pars Plana Vitrectomy



- Vitrector
- **Retrieve IOFB**
 - Forceps
 - Magnet
- Extract IOFB from sclera

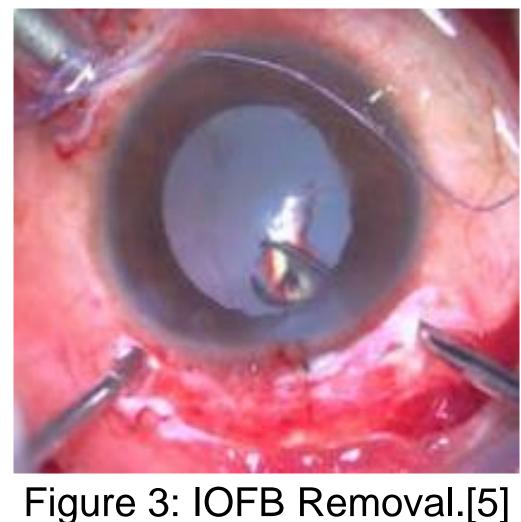
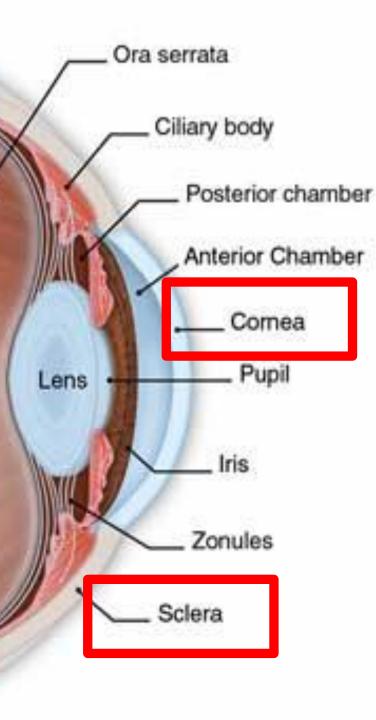


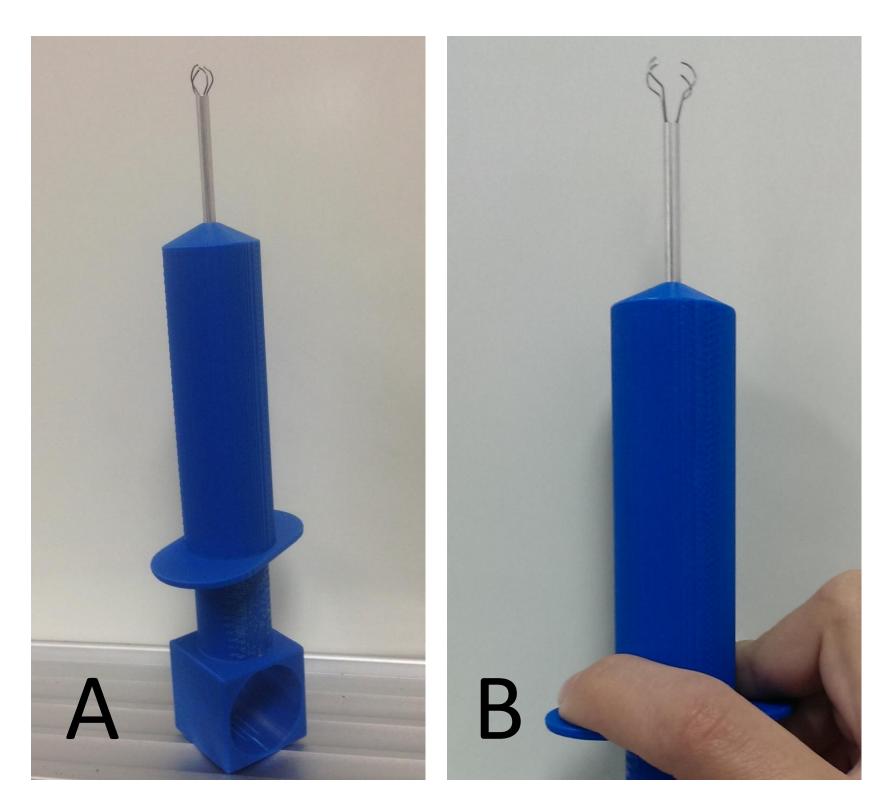
Figure 2: Pars Plana Vitrectomy.[4]

Design Requirements

- Disposable or autoclavable
- Biocompatible
- Minimal entrance wound
- Comfortable no-slip grip
- Intuitive one-handed operation
- Locking grasp around IOFB

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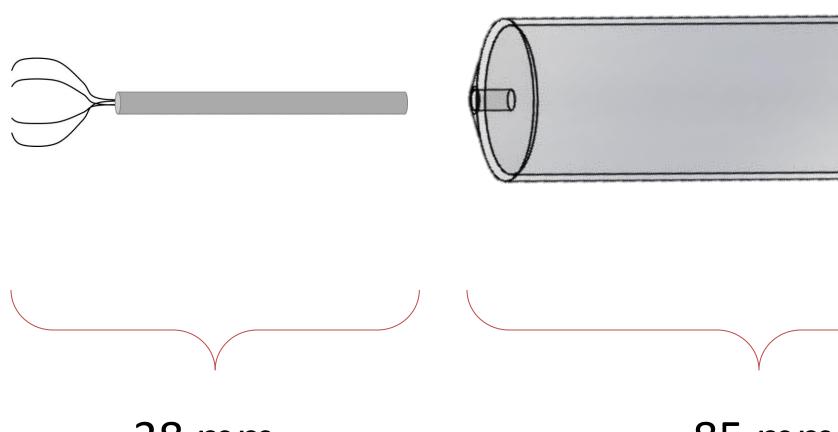


Features:

- Four-pronged claw to grasp IOFB
- Claw retracted into middle rod until released
- Syringe-design handle compresses to release and open claw
- Finger loop for comfort and safe retraction

Handle

- 3-D printed using acrylonitrile butadiene styrene
- Main body inspired by syringe
- Spring fitted inside main body, spring stiffness constant ~ 500 N/m
- Plunger placed inside main body to compress spring and release claw



38 mm

85 mm

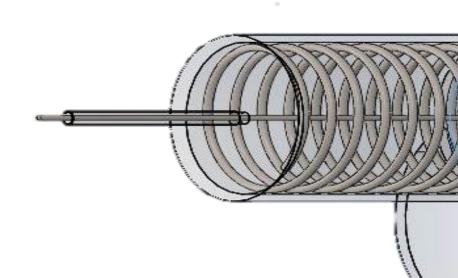


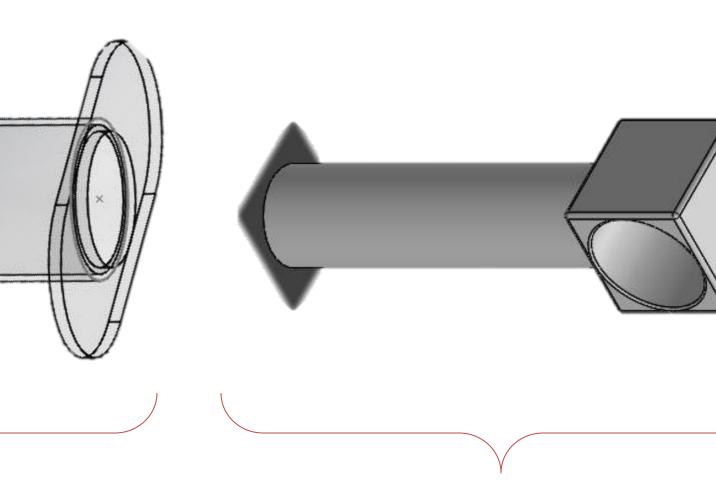
Figure 5: SolidWorks Design of Final Prototype.

Final Design



Figure 4: (A)Final prototype with claw retracted (closed) (B) final prototype with claw released (open) (C) claw grasping airsoft pellet

Prototype Fabrication



60 mm

Testing

Performance Testing

- Task: Pick up an airsoft pallet from the water with vitreous fluid • Current device (forceps) vs. our design (Claw)
- Ten trials measuring for:
 - 1. Required time for successful removal
 - 2. Number of retries required until successful removal
- Averaged values and standard deviation

Results and Analysis

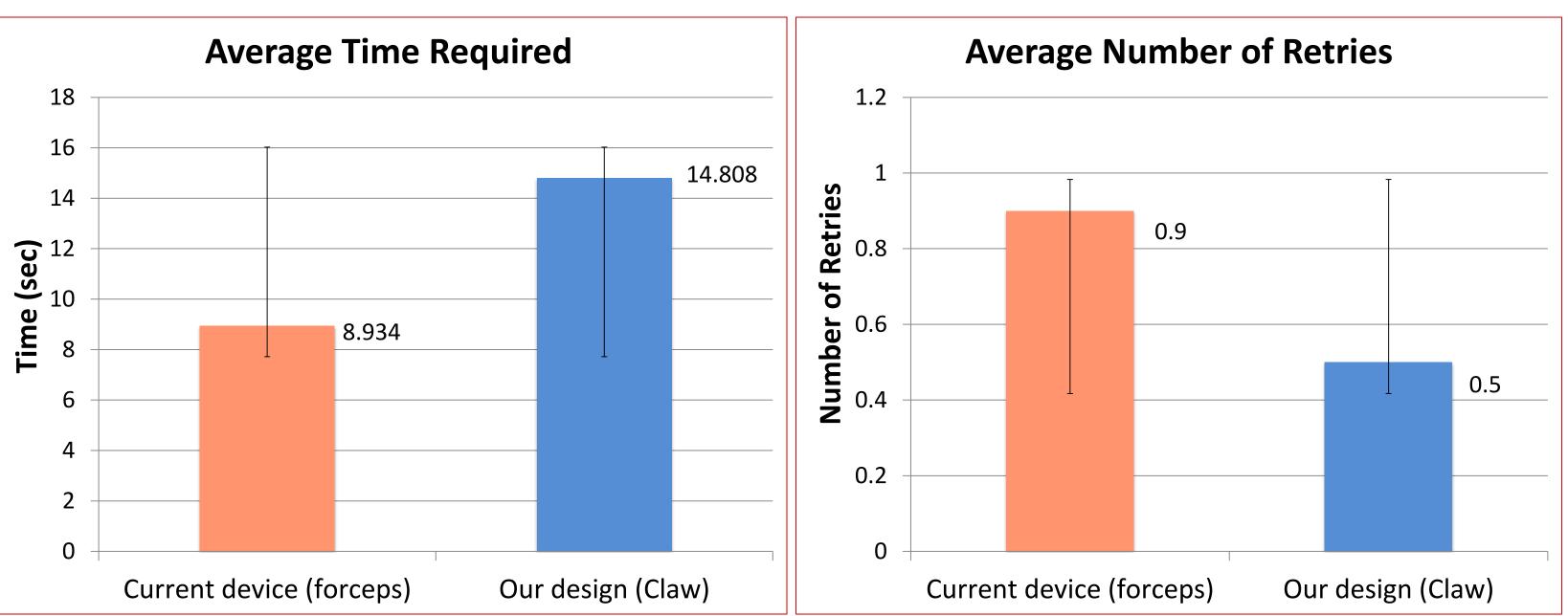


Figure 6: Comparison of Average Time Required for Removal (left) and Number of Retries (right) between Prototype (blue) and Current Device (red).

Current Design and Testing Alterations

- Scale reduction
- Choice of materials
- Professional industrial fabrication
- Refine the prong's design for better performance
- Additional stop-lock mechanism to ensure the protrusion length
- A smooth release mechanism
- More testing on animals

Acknowledgements & References

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Testing & Analysis

Future Work

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