

### Neonatal Intubation Simulation with Virtual Reality and Haptic Feedback

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Dr. Brandon Tomlin

## **Neonatal Intubation**

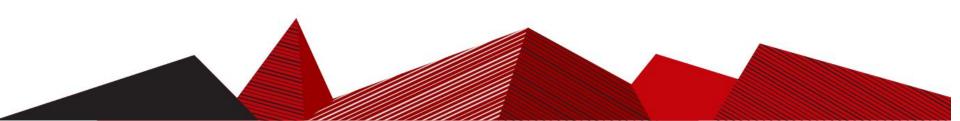
- Intubation may be necessary if the neonate is under respiratory distress
  - Procedure must be done gently, quickly and precisely<sup>1</sup>
- Current training methods are inferior
  - Video Instruction
    - Lack of hands on experience
  - Neonatal Mannequins
    - Inaccurate anatomy
    - Artificially easy





Dr. Ryan McAdams Dr. Brandon Tomlin





# **Specifications and Constraints**

Function:

- Client desires virtual simulation of the neonatal intubation procedure
- Includes haptic feedback
- Requires environment which accurately emulates procedure

#### Performance:

- Must be accurate to 0.02mm to compete with current haptic feedback systems
- Virtual environment must be detailed and load in real time without buffering

#### **Ergonomics:**

• Should feel similar to real procedure in regards to tools used and actions performed

#### **Budget:**

• \$6000 for total simulation

### **Potential Impact**

- 7% of term-newborns undergo respiratory distress<sup>4</sup>
  - Increases substantially in premature infants
- In 2005, nearly 10% of births were premature<sup>5</sup>
  - Highest rates in North America and third world countries

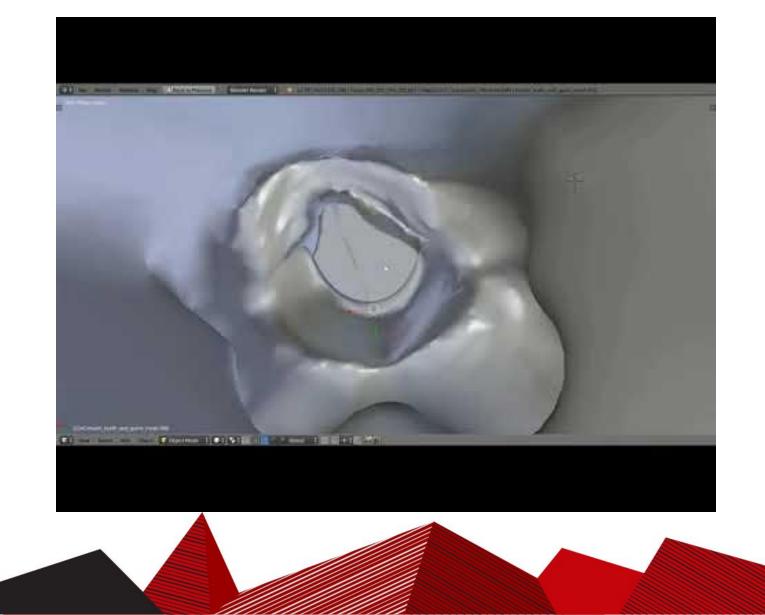
[9]

- Estimated that prevalence increased since 2005
- Anywhere from 30-70% of intubation attempts are unsuccessful<sup>6-8</sup>
- Revolutionize medical procedural training techniques

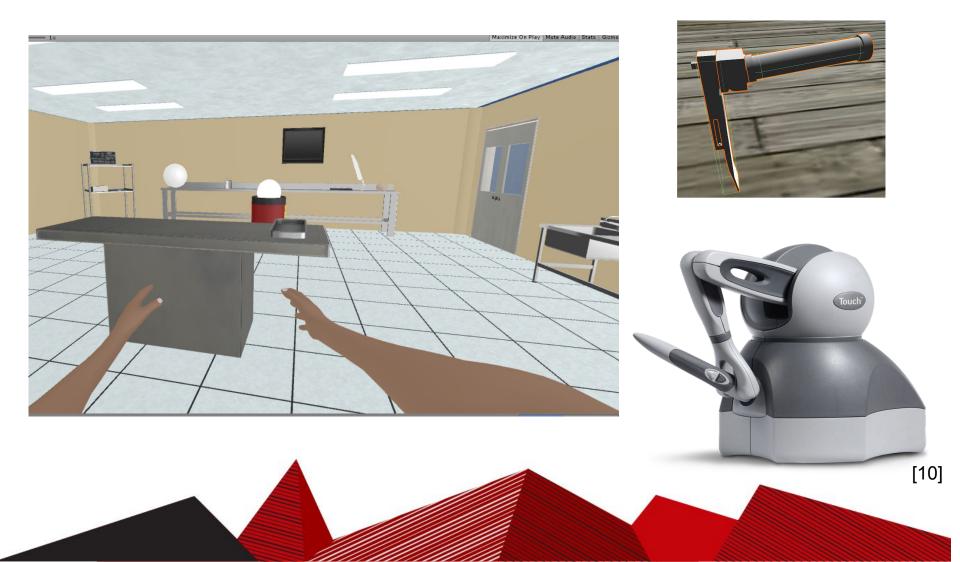
### **Current Prototype - Neonate**



### **Current Prototype - Inner Anatomy**



### Current Prototype -Virtual Environment



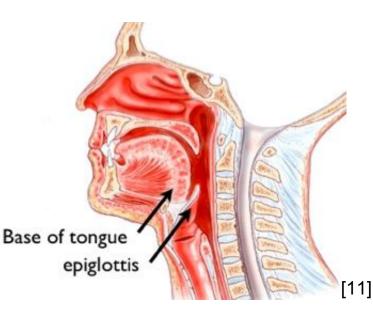
# **Fabrication Challenges**

Programming in Unity provides a challenge

- Extensive knowledge of C# necessary
- Future solution: joint BME/Computer Science design team

Meanwhile, focus efforts on completing neonate model...

- Refining, rigging and texturing
  - Challenges include rigging the tongue and epiglottis, mimicking their flexible and springlike qualities



# **Fabrication Goals**



#### February

Finish prototype of neonate model mesh

- Clean interior anatomy
- Integrate interior anatomy into exterior shell



Complete rigging of internal anatomy

• Refine movement of jaw, tongue, lips, epiglottis and vocal chords

# **Fabrication Goals**

#### ► April

Refine anatomy movement and appearance

- Mimic realistic coloring of baby and anatomy
- Mimic the tongue's soft texture

May

Integrate neonate into Unity environment

• Define equations to simulate realistic feedback when haptic stylus interacts with neonate exterior





# **Future Testing**

- Ultimately, we wish to use this device as a certified surgical training tool
- Objective testing difficult and impractical
- Stage 1:
  - Subjective refinement of environment based on expert feedback (clients, students, other experts)
- Stage 2:
  - Train medical students and residents using either:
    - Traditional methods only
    - Traditional methods + VR simulation
  - Evaluate trainees based on intubation success rates

# **Final Product Overview**

- Final product will consist of:
  - Software
    - Unity simulation with user-friendly interface
      - Multiple difficulty settings
      - User feedback
  - Hardware
    - Dual haptic devices
    - VR headset
    - Access to server
  - Documentation
    - User manual



### **Final Product Overview**

- Overall cost estimate:
  - Haptic devices (\$2200 each, maybe more): \$4,400 \$20,000 [13]
  - Virtual anatomical models: \$69 [14]
  - Unity assets: ~\$200
  - Oculus Rift: \$349 [15]
  - Server access
    - Could build server for: ~\$1,200 \$3,000 [16]
    - Rent from IBM: \$0.39/hour for 8 cores, 32 GB RAM [17]

Total: \$6,000 - \$25,000



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- Our advisor, Prof. Beth Meyerand, for guiding us throughout the preliminary design process
- The BME Department, for providing us with the opportunity to work on this project

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# **Questions?**