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Abstract and Motivation

Breast cancer is the leading cause of cancer death in women [1]. The most common method for combating this disease is a lumpectomy or local tumor removal [2]. This surgery is prefaced by an x-ray imaging procedure in which the tumor is localized using a wire. The procedure is mostly manual, depending heavily on the radiologists' skill levels to get the necessary orthogonal puncture. Most radiologists require repeated corrections and imaging to secure the needle in the correct location, making the procedure very inefficient and uncomfortable for patients. According to Merrill et al., the average time spent on this procedure per patient is 157.7 ± 71.7 minutes, however, the operative time for lumpectomies is only 55.5 ± 16.6 minutes. Thus, this procedure limits the number of lumpectomies performed per day, and reducing procedure time will greatly improve efficiency and save cost for Breast Centers while improving patient comfort. The goal of our product is to standardize this procedure, reduce procedure time, and enhance quality of care.

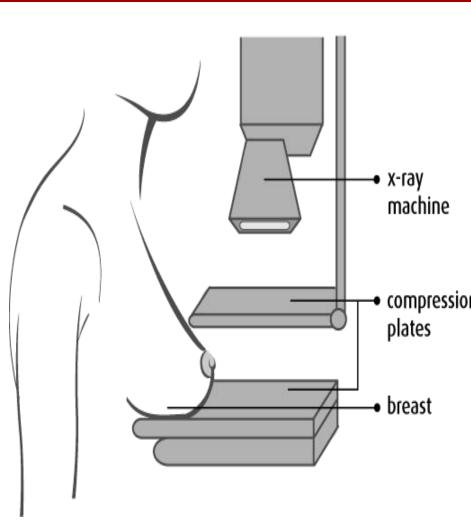
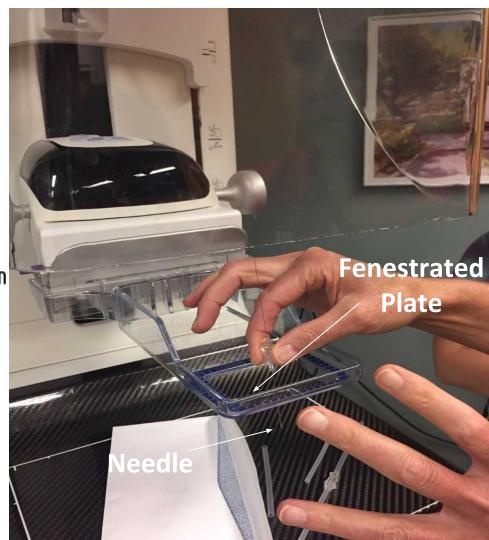
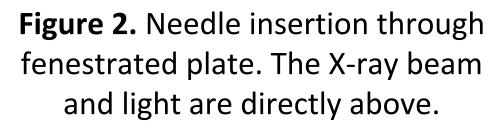
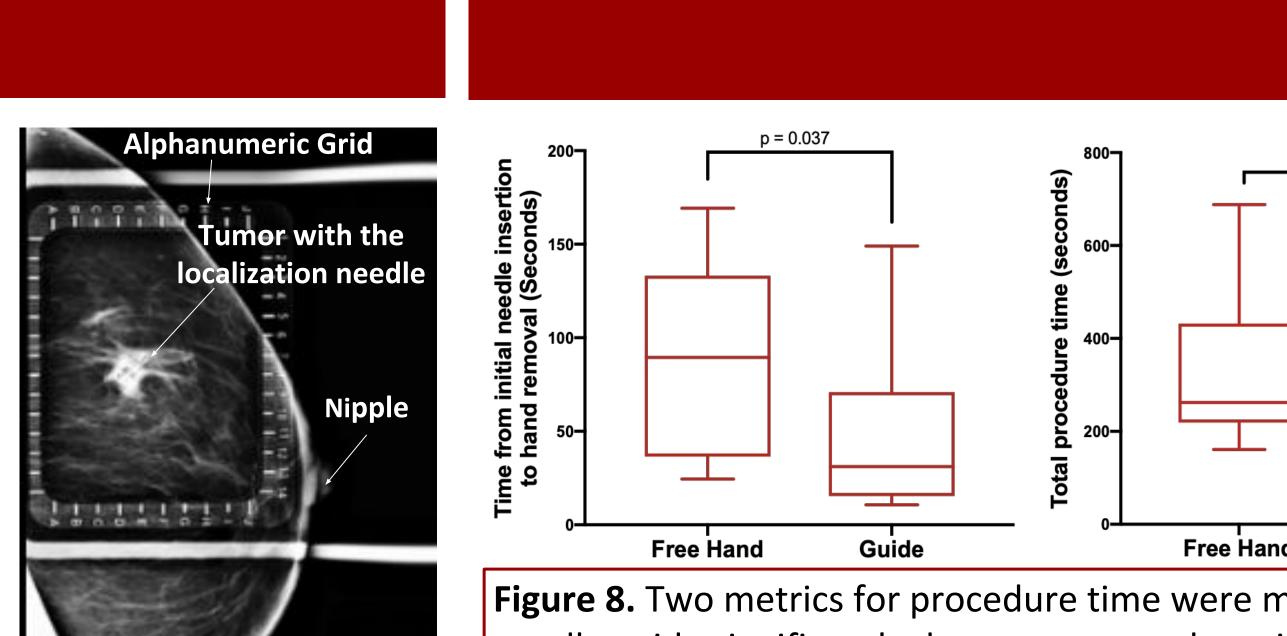


Figure 1. Hologic Mammography machine showing the set-up for imaging [3].

Background







Current Method for Tumor Localization: (1) An initial image is taken with alpha-numeric plate to localize the lesion within the breast, (2) a light is projected in the same direction of the x-ray beam, (3) the shadow of the needle hub assists the needle insertion, (4) the breast is imaged, after needle placement, in the orthogonal plane to ensure perpendicularity and to correct for errors in depth as needed, and finally (5) once satisfied, the needle is removed, leaving the wire in the breast to guide the surgical excision.

Design Specifications

- Perpendicular puncture
- Safe for patients and physicians (i.e. sterile)
- Radio translucent or removable
- Ease of integration in clinics
- Inexpensive
- Decrease number of images necessary in procedure

NEEDLE ALIGNMENT FOR BREAST CANCER LOCALIZATION

Needle-Guide Design Index

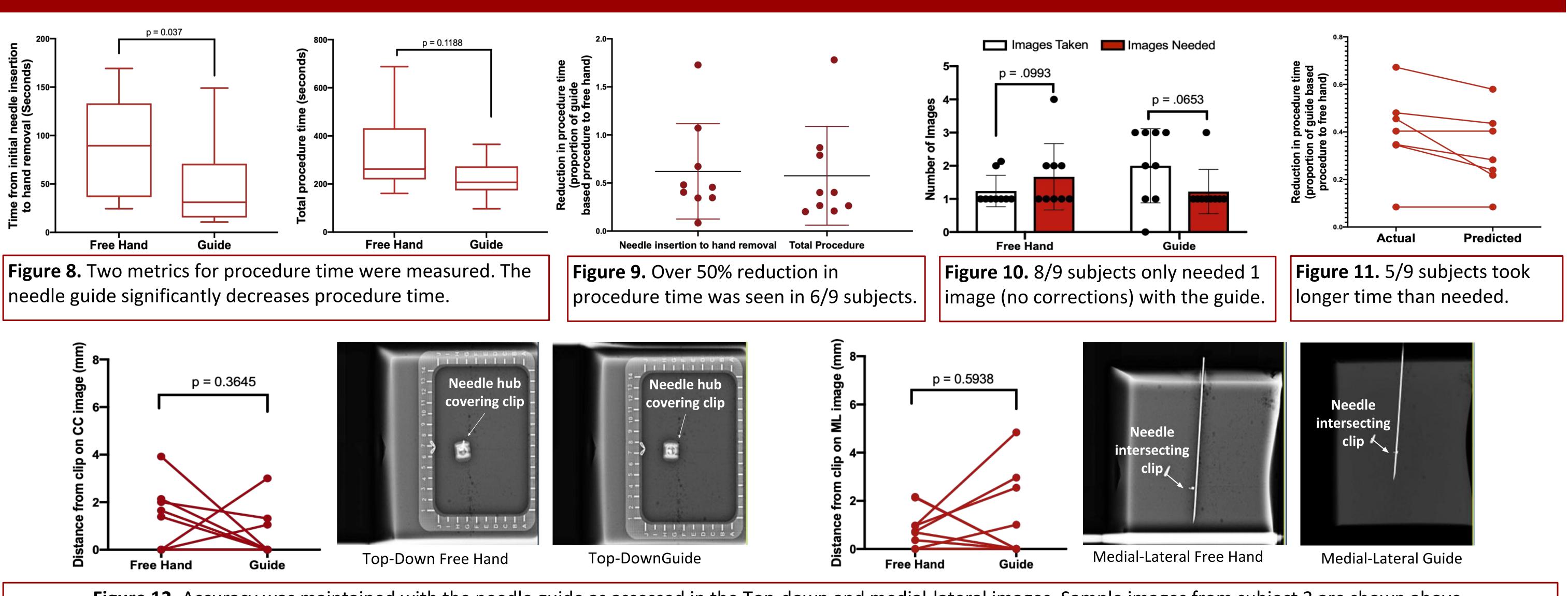


Figure 4. Side-view of needle guide model.

Ring Design:

- Hinges: stability under Z-axis pressure
- Cone: assist with mark localization
- Countersink: accommodates the needle Manufacturing Method: SLA 3D Printer

Figure 3. Mammogram image of needle-wire localization placed through the tumor.



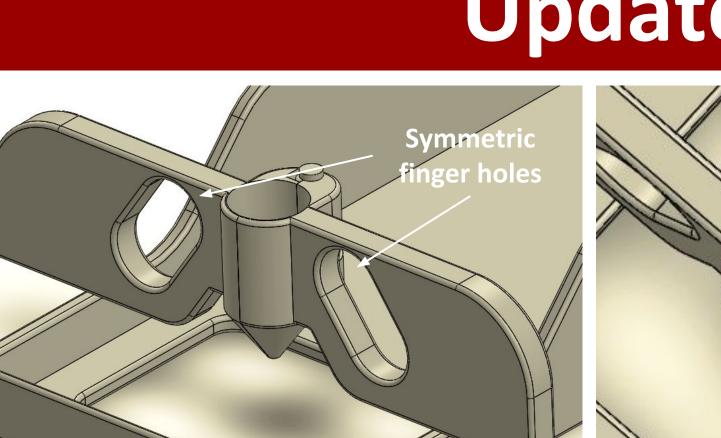
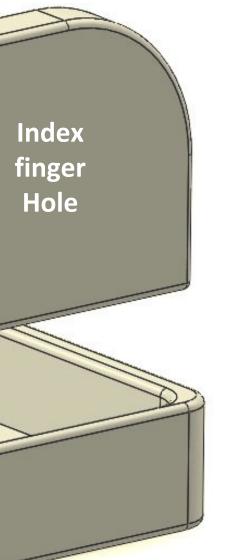


Figure 13. Side-view and top-diagonal view of updated needle guide.



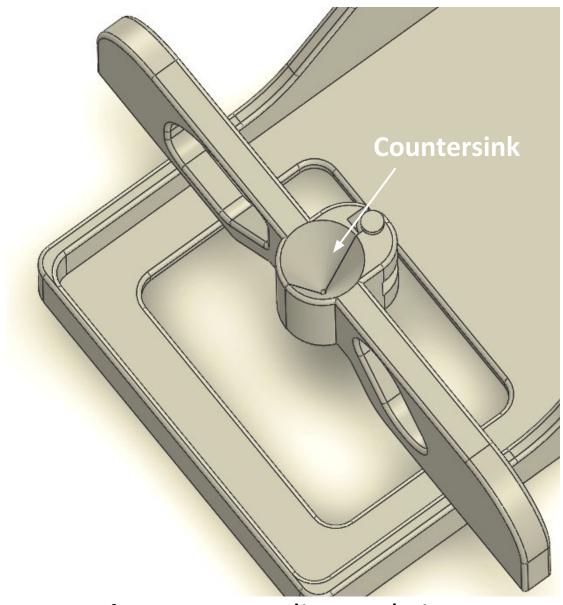


Figure 5. Top-diagonal view.

Perpendicularity: Utilizes lips of the plate to allow for ergonomic positioning and movement of the device while also ensuring accuracy.

Cost per assembly: \$7.80 Grey Pro Resin

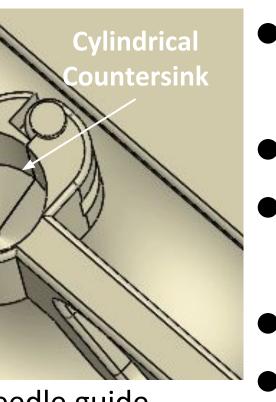


Figure 7a and 7b. Localization using the guide Post Study Survey/ Feedback - 5mins

Results

Figure 12. Accuracy was maintained with the needle guide as assessed in the Top-down and medial-lateral images. Sample images from subject 3 are shown above.

Updated Design



- Updated based on participant feedback • Symmetric finger holes
- Cylindrical insertion chamber
- Modified countersink
- Extended aiming cone

Acknowledgements & References

- Client: Dr. Frederick Kelcz

 UW-Madison Department of Biomedical Engineering [1]R. L. Siegel, K. D. Miller, and A. Jemal, "Cancer Statistics, 2017," Wiley Online Library. [2]"Breast Cancer - Treatment Options", Cancer.Net, 2017. [3]http://media1.s-nbcnews.com/j/newscms/2014_26/181416/140212-mammogram-100 0_d48f27862046309f3cddc1d83d37d8f9.nbcnews-ux-2880-1000.jpg [Accessed 3 Oct. 2017].



Testing Methods

IRB Approved **Metrics**:

- 1. Time from initial needle puncture to final removal
- 2. Total Procedure Time
- 3. Accuracy
- 4. Number images needed (corrections)

Participants:

Any clinician approved to perform localizations **Recruited 9 total**

• Advisors: Dr. Beth Meyerand, Dr. Lonie Salkowski