Title: Low-Interference Wheelchair Footrest

Date: 4/19/2024

Client: Dan Dorszynski Advisor: Dr. John Puccinelli Team:

Charles Maysack-Landry — Leader

Jayson O'Halloran — Communicator

Haoming (Bobby) Fang - BPAG

Sam Tan — BWIG

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Problem statement:

The project aims to innovate wheelchair footrest design to overcome the limitations of current models which are often cumbersome, heavy, and restrict leg movement or access to the ground. The goal is to create a footrest that is lightweight, easily detachable, and foldable, enhancing the wheelchair user's comfort, and allows interactions with surroundings through the footrest.

Brief status update

- Footrest fabrication completed
- Circuit put together
- Testing started

Difficulties / advice requests

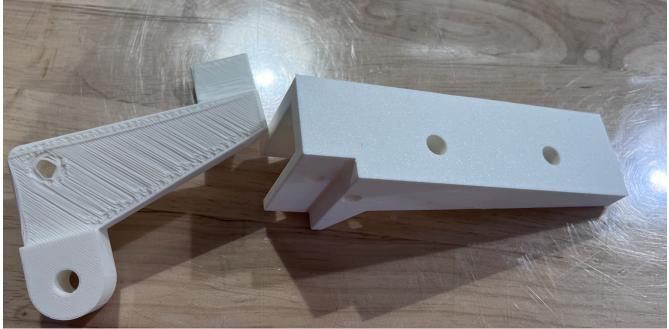
- Continue to look into multiple testing methods
- Load distribution for footrest

Current design:

Current design is a footrest on 2 linear actuators that will be controlled by a button on the wheelchair to move back and forth under the wheelchair.

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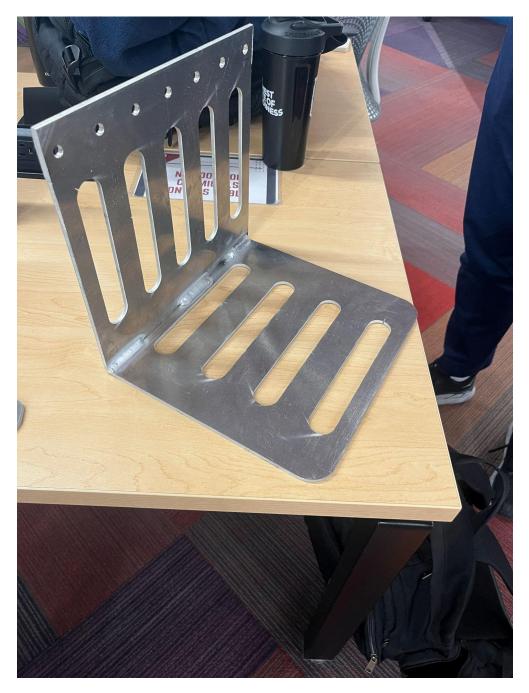




Holder for linear actuator

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Footrest Design



Materials and expenses

ltem	Description		Mft Pt#		Vendor Cat#	Date	#	Cost Each	Total	Link
Linear Motion										
Linear	A device that	Demotor				3/15/	2	\$35.68	\$71.36	https://www.
Actuator	converts	Performance				2024	2	322.00	\$71.50	amazon.com/

Current Total						Total	\$226.10	
Hardwares	Screws, Caps, etc	MakerSpace		Varies		\$1.25	\$1.25	N/A
3D prints	3D prints	MakerSpace		Varies		\$28.1	\$28.1	N/A
MakerSpace H	ardwares + 3D Print	S						-
Zinc ¾ inch threaded screws	Zinc screws	Everbilt		3/18/ 24	1	\$8.98	\$8.98	https://www. homedepot.c om/p/Everbilt -6-x-3-8-in-Zin c-Plated-Philli ps-Pan-Head- Sheet-Metal-S crew-100-Pac k-823322/317 479248
Mounting Bracket for PA-14, PA-14P, PA-08		PROGRESSIVE AUTOMATIONS		3/18/ 24			\$13.92	link
Aluminum	½"x36"x1/8"	MakerSpace		3/15/ 24	3	33	\$99	
Raw Materials							\$0.00	
	straight line.			_	_		ć0.00	4?th=1
	objects in a							p/B00VFXIRW
	to move or control							put-12-Volt/d
	into linear motion							or-Stroke-Out
	rotational motion							Linear-Actuat

Major team goals for the next week

1. Finish fabrication and begin testing

Next week's individual goals

- Jayson
 - Testing
 - Finish final poster
 - Work on final deliverables
- Sam
 - Poster
- Bobby

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- Fabrication/Finish welding
- Testing methods
- Charles
 - Finish fabrication
 - Continue testing
 - Write final report and make the poster

Timeline

Task	Jan		F	eb			March				April				Мау	
Task	26	2	9	16	23	1	8	15	22	29	5	12	19	26	3	10
Project R&D	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
Empathize	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
Background	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
Prototyping								Х	Х	Х	Х	Х	Х			
Testings												Х	Х			
Deliverables																
Progress Reports	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
PDS			Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
Prelim presentation						Х										
Final Poster																
Meetings																
Client			Х			Х		Х		Х		Х	Х			
Advisor	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
Website	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			
Update	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х			

Filled boxes = projected timeline

 \mathbf{X} = task was worked on or completed

Previous week's goals and accomplishments

- Sam previous goal
 - 3D printings
- Bobby previous goal
 - Fabrication and testing protocol
 - Meeting with welding expert
- Charles previous goal
 - Fabricate
 - Test
- Jayson previous goal
 - Finish Fabrication
 - Begin final poster
- Team previous goal 6
 - Begin fabrication
 - Welding, water jetting, circuit, 3D printing

Activities

Name	Date	Activity	Time (h)	Week Total (h)	Sem. Total (h)
Sam	4/19/2024	CAD, 3D printing	3	3	35
Bobby	4/12/2024	Fabrication/Welding setup	2	2	28
Jayson	4/19/2024	Fabrication of footrest and circuit box screw holder	5	5	45
Charles	4/19/2024	Fabrication of footrest and circuit box, Circuitry, Ethics in engineering paper	6	6	42