



## ABSTRACT

Laboratory procedures often necessitate extensive use of wrists and hands. The current procedure at a local lab requires each technician to open a large number of containers each day, involving tremendous hand stress and strain. A device is desired to significantly reduce this hand strain during the opening of containers. While manual and automatic container-opening devices are currently on the market, they are targeted for consumer use rather than industrial or laboratory use. More specifically, the majority of automatic container-opening devices do not have the power to open containers fast enough for the technicians of concern, thus these devices would reduce their productivity. A new, automatic device is being proposed to specifically meet the technician's needs; most importantly, the device will be designed to significantly reduce hand strain without negatively affecting workflow.

## PROBLEM DEFINITION

### MOTIVATION:

- A local commercial food-testing laboratory employs over 400 technicians
- Technicians are required to repeatedly cap and uncup laboratory containers
- Each technician follows a procedure, which involves the uncapping and capping of 50-100 containers per day.
- The repetitive counter-twisting motion that these technicians exhibit daily leads to significant strain on their hands, wrists and fingers.
- The goal is to reduce this discomfort by developing a container opener tool or stationary fixture that assists in the opening of variably-sized containers.



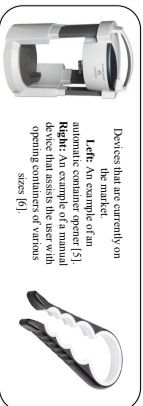
Laboratory containers that represent the containers that the device will be used to open [3]

### BACKGROUND:

- The client collaborates with a local laboratory that is interested in ergonomic factors to protect the well-being of its employees.
- An ergonomic container opener is needed because:
  1. Repetitive hand motion has been found to cause basal joint arthritis [1].
  2. The torque required to open containers has been found to be extremely difficult for most users [2].
- Many devices on the market, but none meet the need because they are:
  - *Low durability*
  - *Inefficient*
  - *Do not reduce hand strain sufficiently*



Representation of the wearing of the basal joint arthritis in a hand from arthritis in a thumb and proximal phalanx [4].



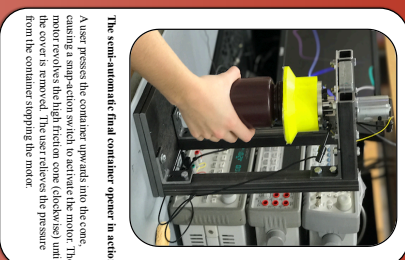
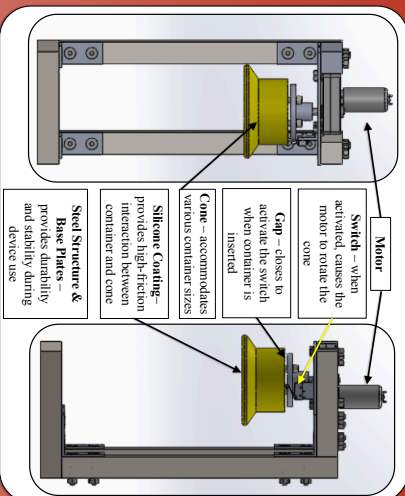
## DESIGN CRITERIA

1. Significantly relieve the hand strain caused from the repetitive opening of containers
2. Open containers with minimal manual intervention → One hand
3. Open containers without interrupting workflow or production → Meet quotas
4. Open at least 100 bottles per day per technician
5. Single device to open containers ranging from 1.25" to 3.5" in diameter
6. Maintain function for over at least 10,000 hours of use
  - The motor's lifetime is approximately 10,000 hours [7]
  - All structural materials should tolerate use for over 10 years
7. Be capable of undergoing sterilization
8. Be safe for the user to operate
9. Cost no more than standard laboratory equipment, ~\$500-\$1000



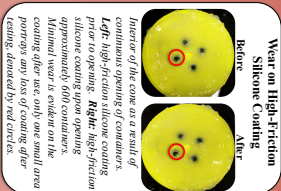
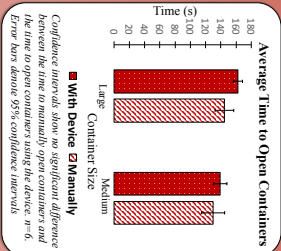
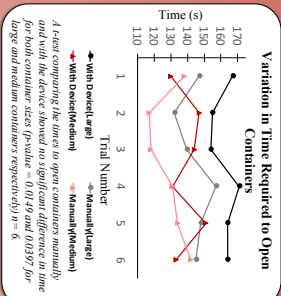
Visual representation of a workflow pattern [8].

## FINAL DESIGN



The semi-automatic final container opener in action. A user presses the container upwards into the cone, the motor revolves the high friction cone clockwise until the cover is removed. The user relieves the pressure from the container stopping the motor.

## TESTING



## FUTURE WORK

- Develop conveniently interchangeable cones to accommodate even more container sizes
  - Our final device accommodates containers with cover diameters of 1.7" – 3.5"
- Fabricate a protective shield to cover the cone, hub, and motor components of the device
  - This would further ensure safety of the device while in use
- Produce more devices identical to the final design
  - This would allow more technicians access to a container opener, therefore reducing hand stress and strain for a greater percentage of laboratory employees
- Provide a power supply for the device
  - The motor in the final device is a 24 V DC gear motor, meaning that it requires either a direct DC power supply or a DC to AC transformer
  - A transformer provides the capability to convert input AC voltage to output DC voltage, which is necessary for the motor plus to power the device via traditional wall outlet [9].
  - A DC power supply provides the capability to supply a fixed voltage or current to the device [10].

## ACKNOWLEDGEMENTS/REFERENCES

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[1] Hobbie, Robert, M.D. et al. "A System to Measure the Incidence of Occupational Syndrome Reported by 123 X-Ray Technologists." *Journal of Occupational Rehabilitation*, 1992, pp. 10-15. [2] A. Yeh and J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [3] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [4] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [5] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [6] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [7] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [8] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [9] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104. [10] J. S. Chaffin, "The Effect of Hand Force on the Torque Required to Grip a Tool," *IEEE Transactions on Systems, Man, and Cybernetics*, 1990, pp. 100-104.