

Advisor: Dr. William Murphy
Clients: Dr. McLean Gunderson



DEPARTMENT OF
Biomedical Engineering
UNIVERSITY OF WISCONSIN-MADISON
3D Printed Anatomy Models for Vet Students

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Team Members

From left to right:

Cora Williams (Communicator)

Maggie LaRose (BPAG)

Molly Paras (BSAC)

Lauren Fitzsimmons (Co-Leader)

Zach Spears (Co-Leader)

Emily Hutsell (BWIG)

Advised by Dr. Bill Murphy

Client Dr. McLean Gunderson



Overview

- I. Problem Statement/Background
- II. Client Information/Requirements
- III. Product Design Specifications
- IV. Design Options/Design Matrices
- V. Final Design and Future Work
- VI. Acknowledgements/References





Problem Statement

- First year veterinary students learn anatomy of canines
- Cadavers pose ethical, safety, and monetary concerns [1]
- 3D printing as a viable alternative
 - Cheaper, safer, more durable [2]
- 3D printed model of a right canine hindlimb
 - 3D printed bones
 - Accurate muscle depiction and insertion
 - Realistic muscle flexion and extension

Background

- First year veterinary students benefit from hands-on learning
- 3D animal models for teaching demonstrations and experimental processes
- Many models lack important anatomical characteristics:
 - Joints and ability for movement
 - Accurate muscle insertions and origins
- Cost
 - \$2500 for the one pictured

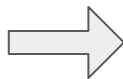


Figure 1. Canine Bone Model [1]

Competing Designs



Figure 2. Axis Scientific Canine Hindlimb with Foot [2]

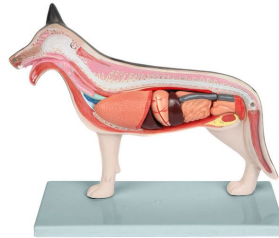


Figure 3. Anatomy Lab Domestic Canine (*Canis lupus familiaris*) Anatomy Model [3]



Figure 4. Dr. McLean Gunderson's Preliminary Model

Client Information



Figure 5. Dr. McLean Gunderson [4]

- Dr. McLean Gunderson
- Researcher and Professor
 - Small and Large Animal Anatomy
- Previously:
 - Senior Instructional Specialist for the Department of Surgical Sciences
 - Veterinarian
- Passion for innovation
 - 3D teaching models



Client Requirements

Anatomically
Correct

Accurate
muscle
insertion
points

\$500 Budget

Realistic
muscle
flexion and
extension

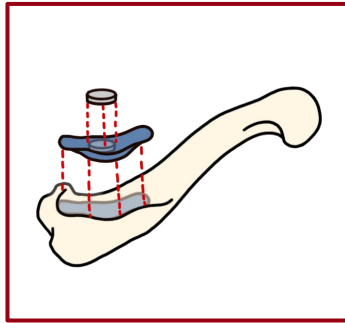
For
First-Year
Anatomy
Students

Product Design Specifications

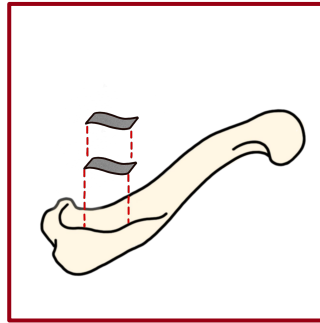
1	Accuracy	Must represent canine hindlimb bones and muscles to 95% degree of accuracy according to survey of veterinary students
2	Durability	Should withstand 180° flexion/extension (100 times) with no measurable decrease in attachment force
3	Reliability	Must attach/detach at the correct surface areas of real canine anatomy, according to <i>Miller's Anatomy of the Dog</i>
4	Life in Service	May be used by 96 students up to 12 hours a week for 5 years



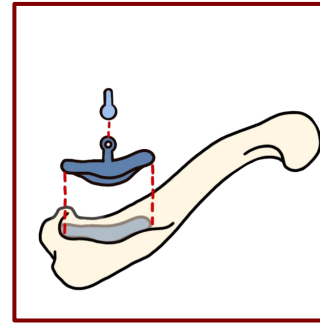
Design Matrix 1: Muscle Attachment Mechanisms



1.



2.



3.

Figure 6. Three Muscle Attachment Mechanisms Design Options



Design 1: Magnets

- 3D printed piece in the shape of actual muscle attachments
 - Magnets in bone and attachment piece

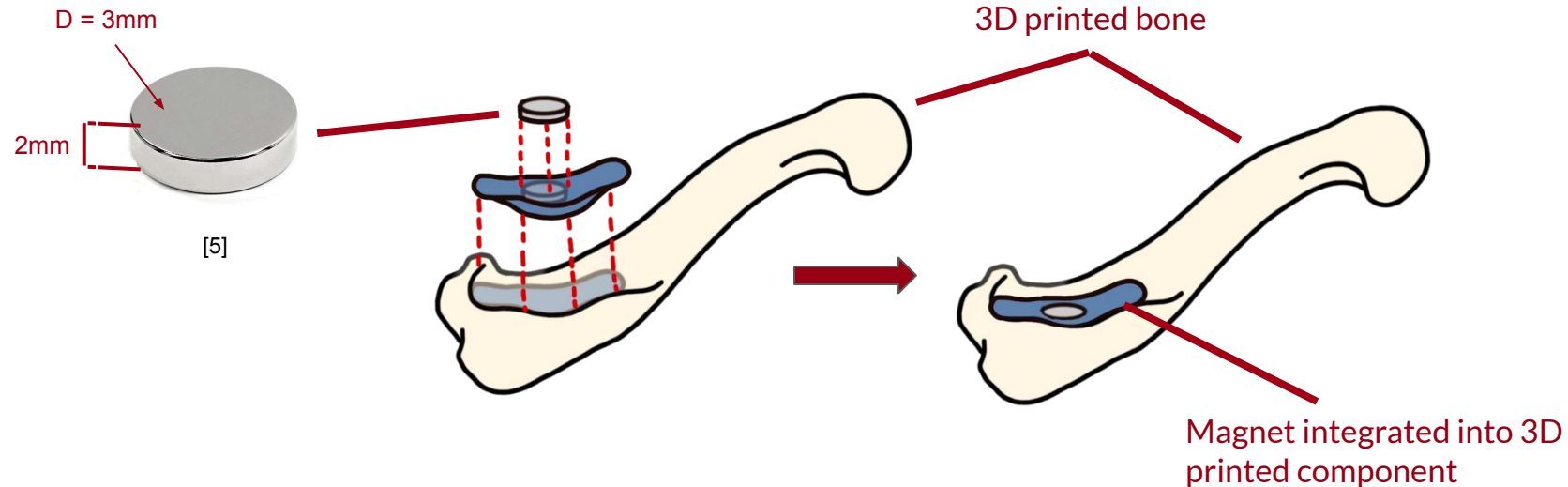


Figure 7. Neodymium Magnet Attachment Mechanism



Design 2: Velcro

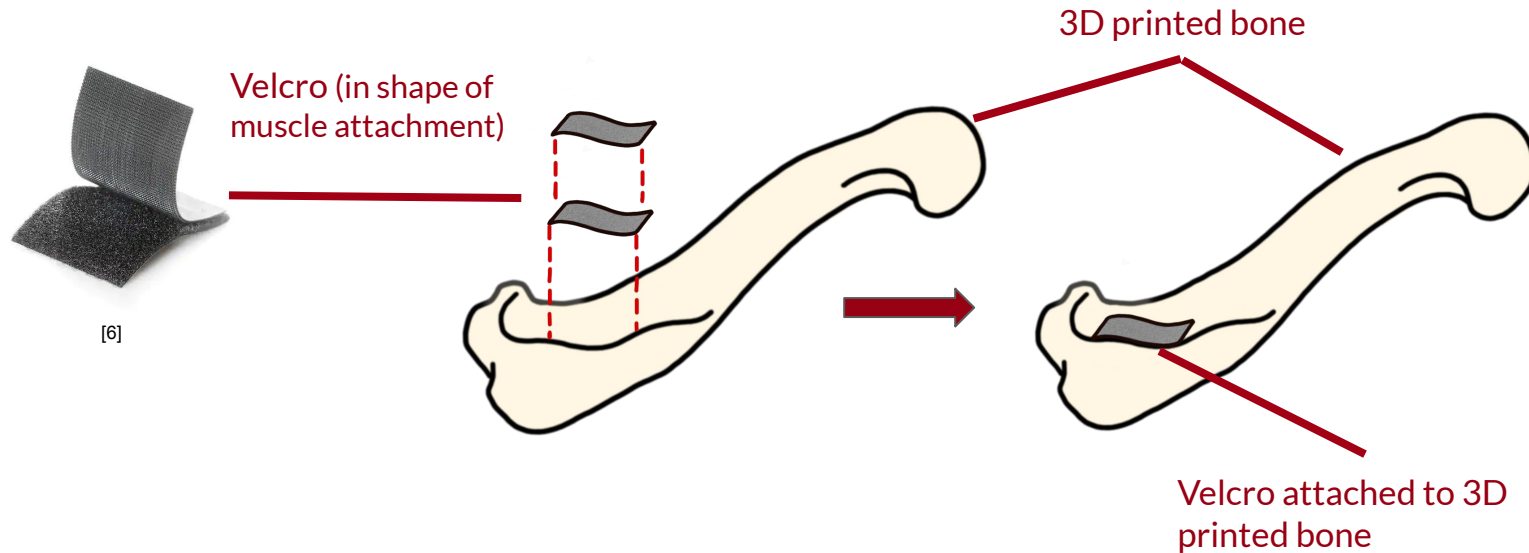


Figure 8. Velcro Strip Attachment Mechanism



Design 3: Hooks

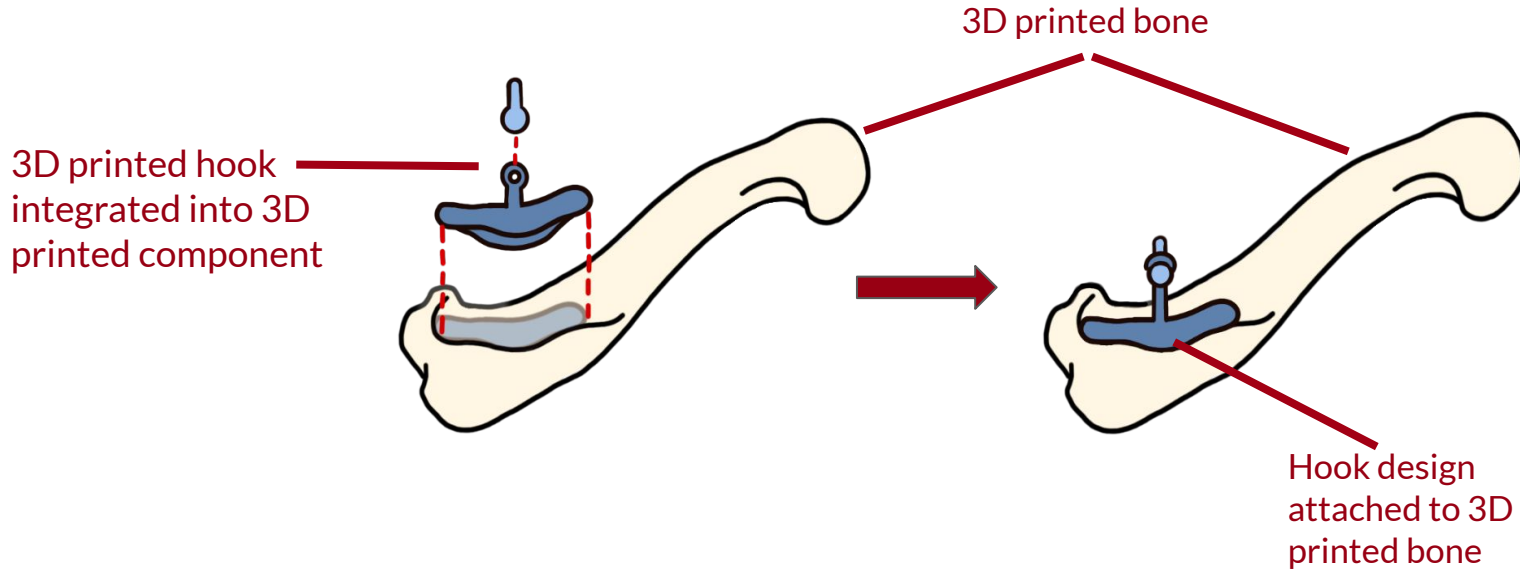


Figure 9. Hook Attachment Mechanism



Design Matrix 1 Criteria

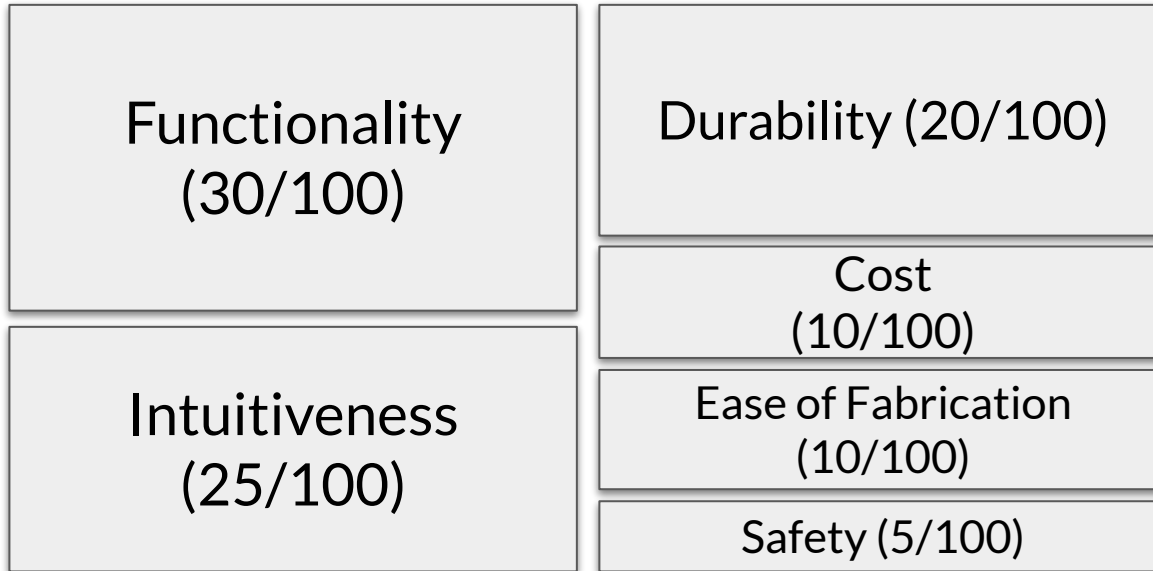
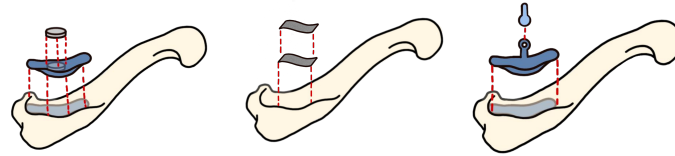


Figure 10. Design Matrix 1 Criteria

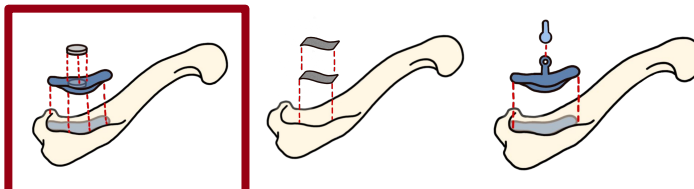
Design Matrix 1



Design		Magnets		Velcro		Hooks	
Criteria	Weight						
Functionality	30	5/5	30	2/5	12	1/5	6
Intuitiveness	25	5/5	25	4/5	20	3/5	15
Durability	20	4/5	16	1/5	4	1/5	4
Cost	10	3/5	6	5/5	10	4/5	8
Ease of Fabrication	10	3/5	6	4/5	8	3/5	6
Safety	5	3/5	3	5/5	5	4/5	4
Total	100.0	86/100		59/100		43/100	

Figure 11. Design Matrix

Design Matrix 1



Design		Magnets		Velcro		Hooks	
Criteria	Weight						
Functionality	30	5/5	30	2/5	12	1/5	6
Intuitiveness	25	5/5	25	4/5	20	3/5	15
Durability	20	4/5	16	1/5	4	1/5	4
Cost	10	3/5	6	5/5	10	4/5	8
Ease of Fabrication	10	3/5	6	4/5	8	3/5	6
Safety	5	3/5	3	5/5	5	4/5	4
Total	100.0	86/100		59/100		43/100	

Figure 12. Design Matrix



Design Matrix 2: Muscle Materials

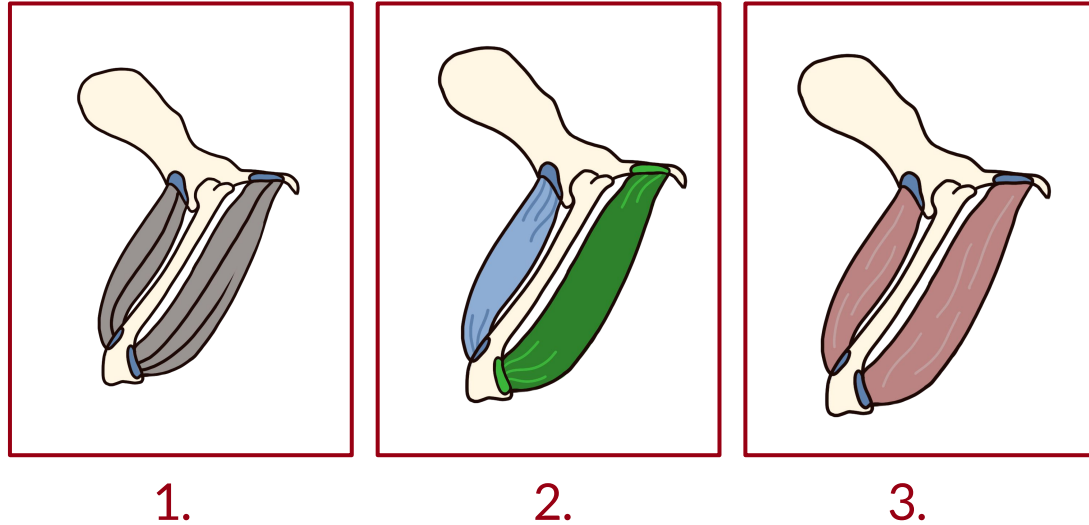


Figure 13. Three Muscle Material Design Options



Design 1: Latex

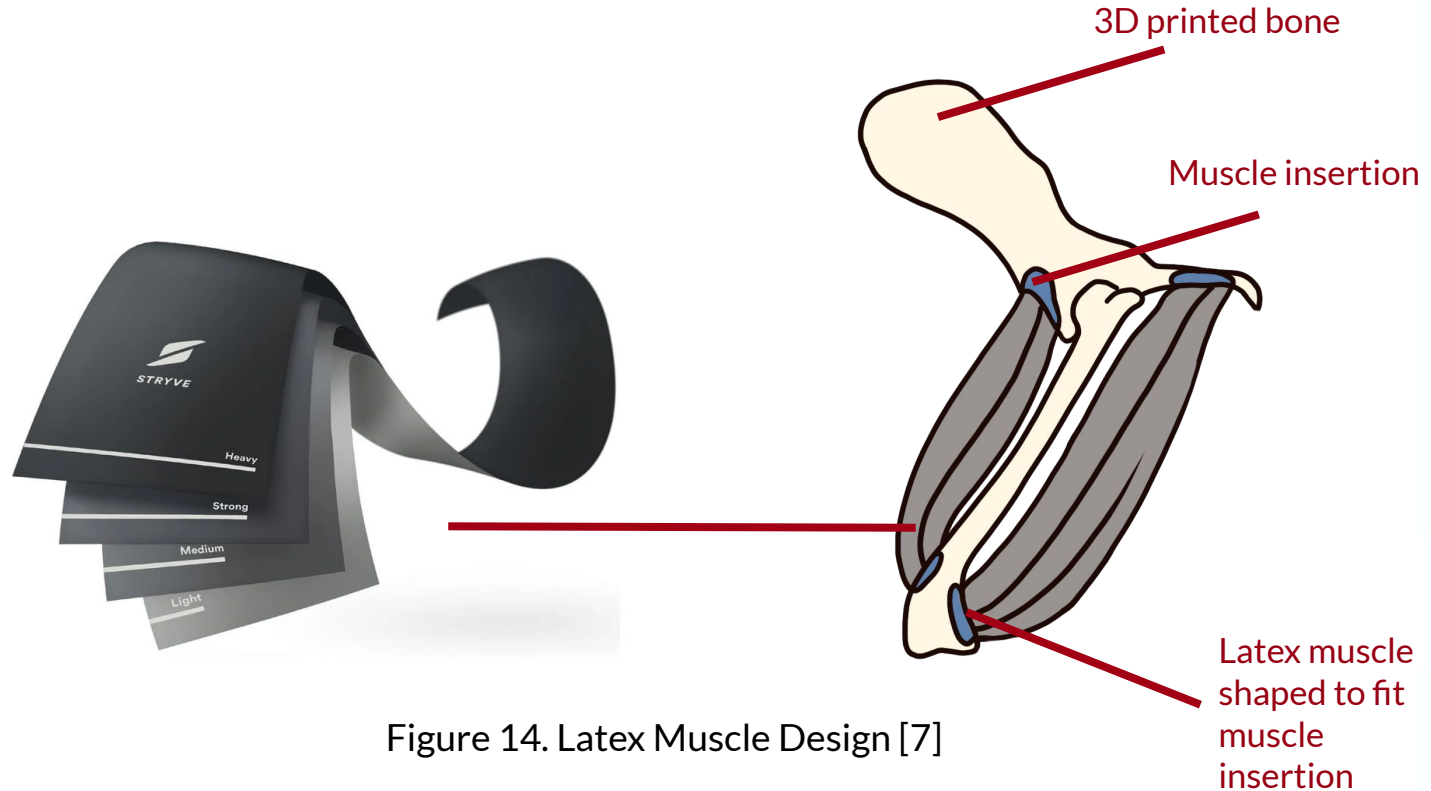


Figure 14. Latex Muscle Design [7]

Design 2: Fabric (Nylon/ Spandex)

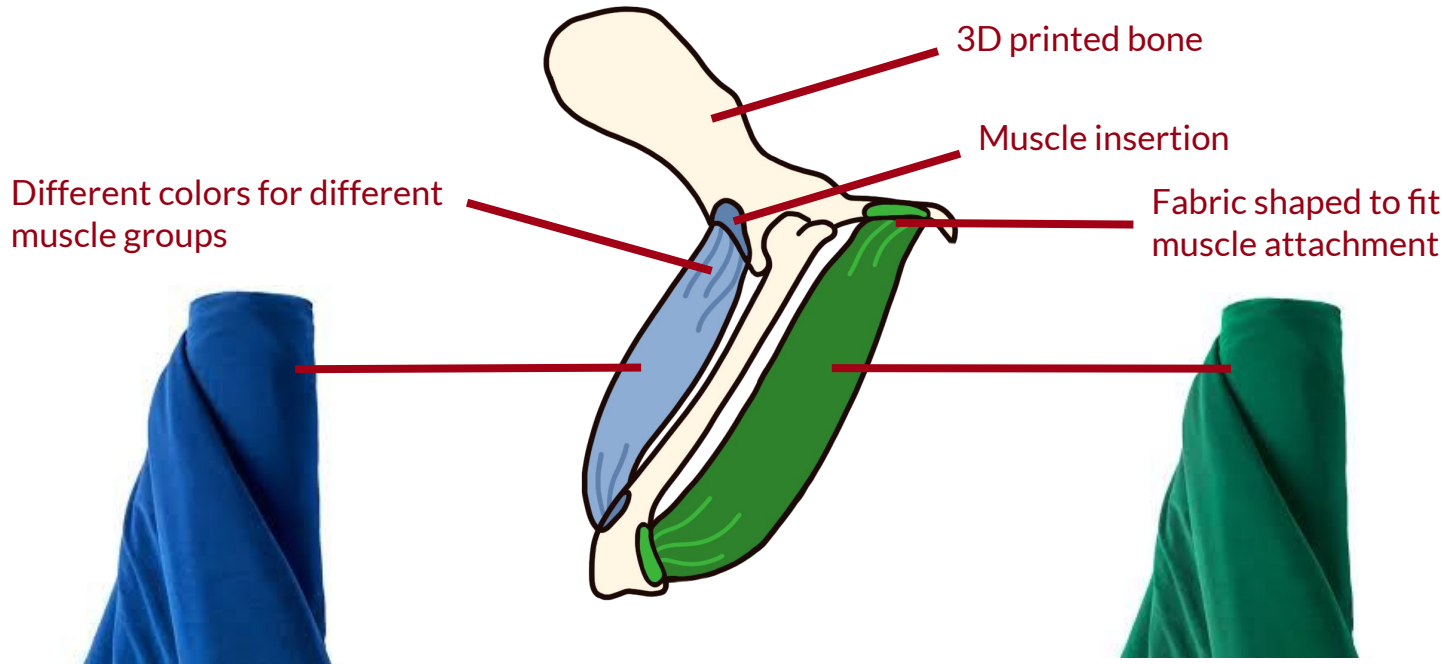
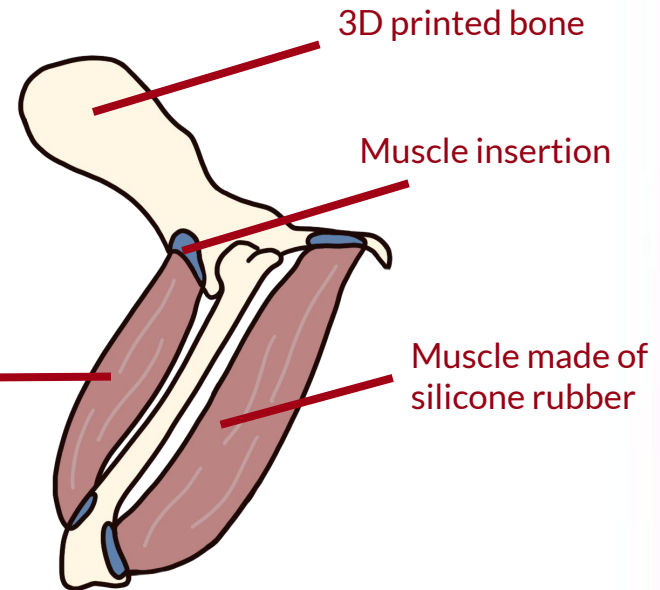


Figure 15. Fabric Muscle Design [8,9]

Design 3: Silicone Rubber (Ecoflex)

- Pour silicone rubber and cure in individual muscle molds

Molding technique
used to create
individual muscles



[10] Figure 16. Silicone Rubber Muscle Design



Design Matrix 2 Criteria

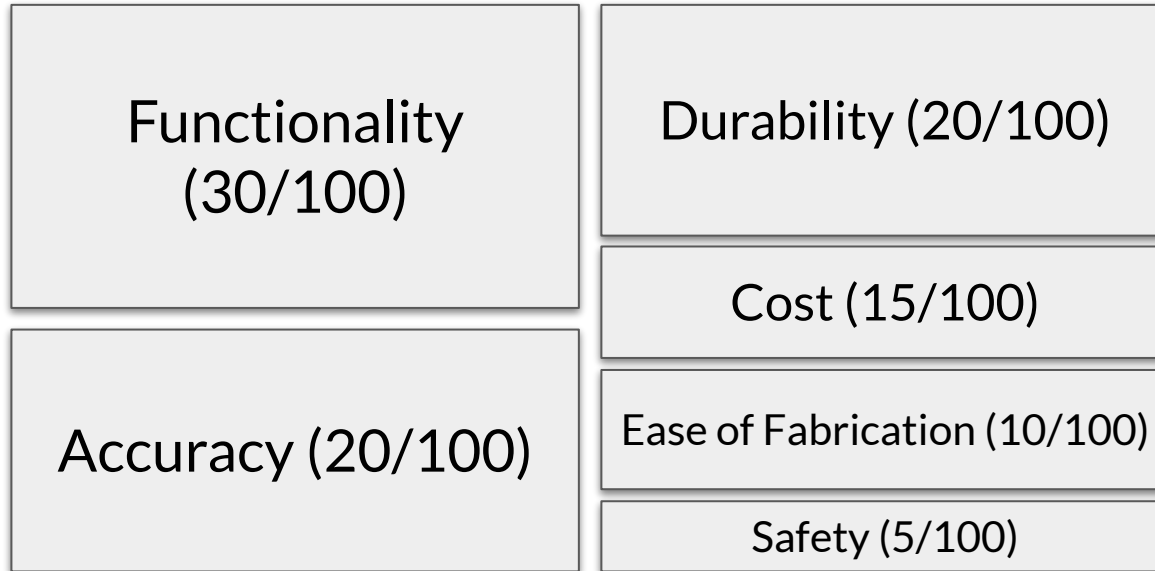
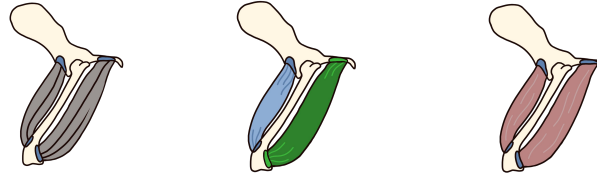


Figure 17. Design Matrix Criteria

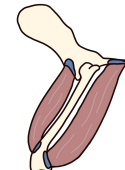
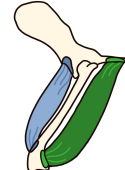
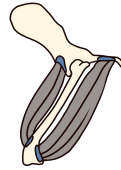
Design Matrix 2



Design		Latex Band		Fabric (Nylon/ Spandex)		Silicone Rubber (Ecoflex)	
Criteria	Weight						
Functionality	30	3/5	18	4/5	24	2/5	12
Accuracy	20	2/5	8	5/5	20	4/5	16
Durability	20	4/5	16	5/5	20	4/5	16
Cost	15	5/5	15	4/5	12	2/5	6
Ease of Fabrication	10	4/5	8	3/5	6	2/5	4
Safety	5	4/5	4	2/5	2	5/5	5
Total	100.0	69/100		84/100		59/100	

Figure 18. Design Matrix

Design Matrix 2



Design		Latex Band		Fabric (ex. Spandex)		Silicone Rubber (Ecoflex)	
Criteria	Weight						
Functionality	30	3/5	18	4/5	24	2/5	12
Accuracy	20	2/5	8	5/5	20	4/5	16
Durability	20	4/5	16	5/5	20	4/5	16
Cost	15	5/5	15	4/5	12	2/5	6
Ease of Fabrication	10	4/5	8	3/5	6	2/5	4
Safety	5	4/5	4	2/5	2	5/5	5
Total	100.0	69/100		84/100		59/100	

Figure 19. Design Matrix



Final Design: Magnet Integrated Fabric Muscle 3D Model

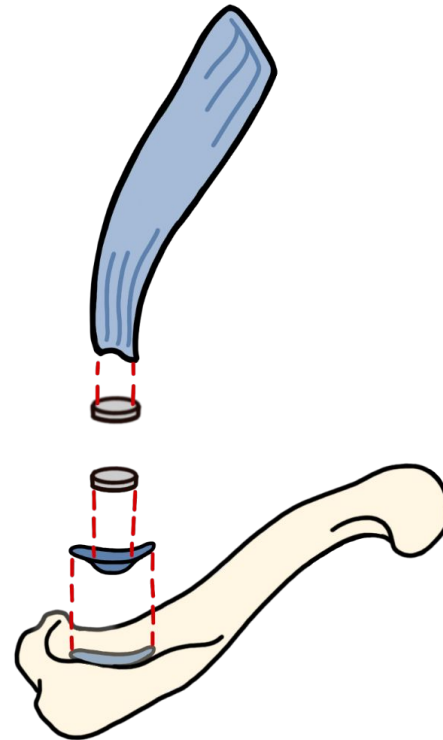


Figure 20. Final Design: Magnet Integrated Fabric Muscle 3D Model



Final Design: Magnet Integrated Fabric Muscle 3D Model

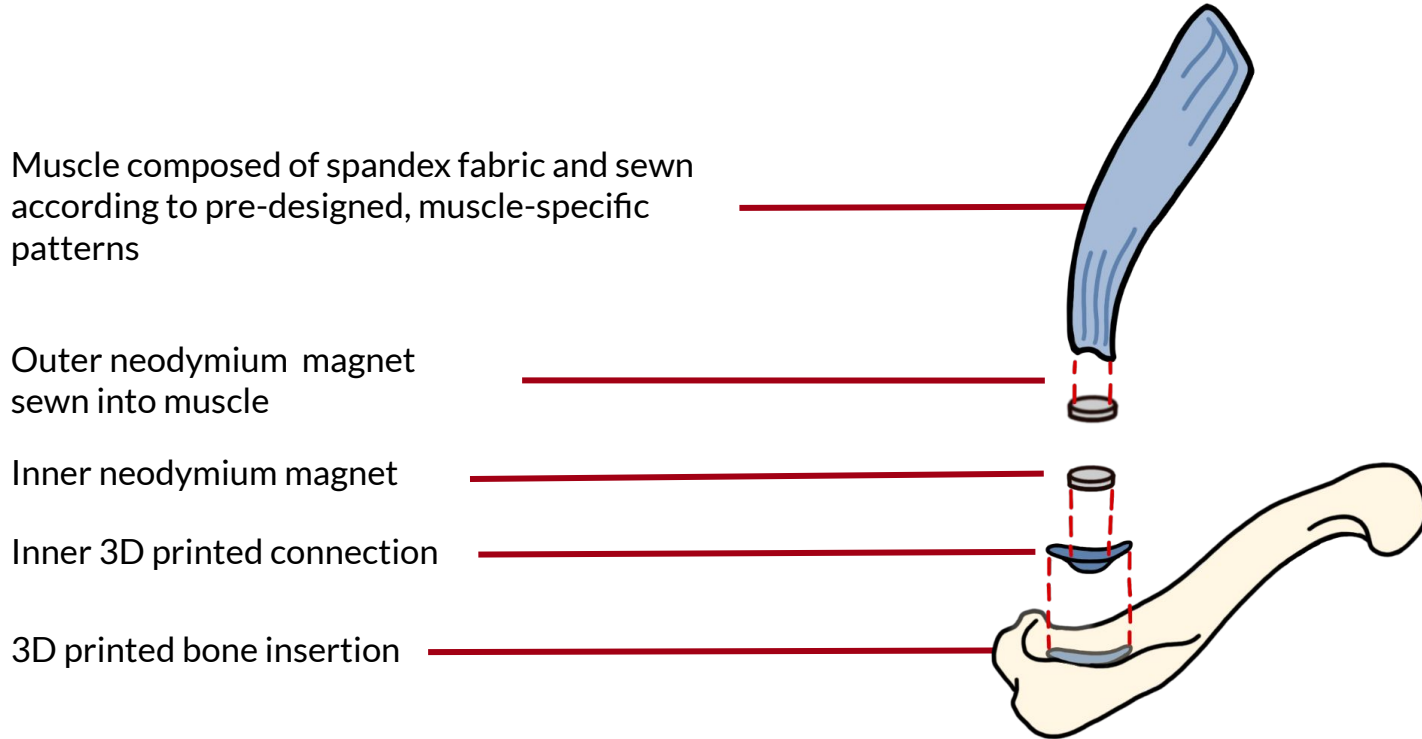


Figure 21. Final Design: Magnet Integrated Fabric Muscle 3D Model



Future Work

Phase 1:

3D scan and print bones

Phase 2:

3D print muscle attachment components

Phase 3:

Design, sew, and fabricate spandex muscle model

Phase 4:

Prototype evaluation and testing



Acknowledgements

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Questions



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