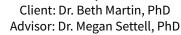
# **ALERT DEVICE FOR WALKER (WARNS)**

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Future Work - Convert from solenoid to a linear actuator [9]

be needed in future iterations

correct response to occur

- Minimize size of circuit box and use a more secure
- fastener
- Conduct a focus group to see if potential users think the device would be useful
- Research and implement portable battery for power

#### source Conclusion

Figure 14. L9110 Linear Actuator [8]

The team observed that each condition exceeded the goal success rate of 80% for the semester, therefore it was deemed that the design has potential for continuation at a later date. The team also noted further advancements that could be made in several areas of the project that would have been achieved with an extended timeline.

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Limitations

therefore a more powerful microcontroller or a new interface may

different Arduino library may need to be added to the code for the

**Future Work and Conclusion** 

- The code, despite having a 15 second delay, causes an instant

response from the speaker and solenoid in case 4, therefore a

- The Arduino is limited to 5 V of power, and 12 V maximum.

### Acknowledgements

The team would like to thank Dr. Settell for her guidance and support, along with Dr. Martin for her flexibility and involvement in the project. In addition, the team would also like to thank Dr. Nimunkar and Dr. Coventry for their help with Arduino coding and Dr. Fields for her guidance with testing guidance and feedback.

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### Abstract

47,000 older adults are injured annually from falls related to walkers and canes [1]. Use of assistive walking devices can lead to loss of independence or even embarrassment. Walker designs on the market are primitive, lacking comfort and proper safety features. Current lock technology uses pressure-based designs, however there are several factors that undermine the effectiveness of the locks, such as uneven terrain or physical impediments [2]. Designing a more effective lock and alert is integral for improving safety and decreasing injury.

## **Background and Motivation**

 Most walker users have less inclination to use the safety aspects of a walker [3] -Elderly adults may not have enough strength or control to stop the walker by themselves [2] Competing design found was a self locking mechanism



Figure 1. Dolomite Figure 2. Self locking Legacy 600 Walker [9] brake mechanism [2]



Device cannot be restrictive, heavy or require large force to operate[4]

- Adults aged 74-85+ will use this product [5]
- Must comply with FDA [6] and ADA [7] restrictions \$300 budget

# Figure 5. Walker front view

#### Materials:

- Arduino Uno Rev3 - Breadboards (2) - Walker
- SP-3605 Speaker Adafruit Solenoid
- PLA (circuit box) Grove → Touch Sensor - Wires, resistors, transistors,





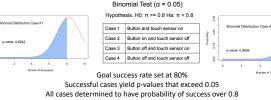


Figure 6. Alert system on walker

