Motion Stage for Optical Coherence Tomography

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Agenda

- Introduction to OCT
- Why we need a motion stage
 - Specifications and constraints
- Solutions
 - Last semester's work
 - Goals for this semester
 - Testing the device
- Future Work

Optical Coherence Tomography: Background

- Micrometer resolution
- Allows diagnosis of conditions like macular degeneration
- Uses principles of low coherence interferometry

Problem Statement and Specifications

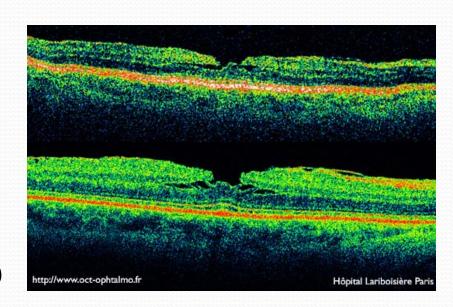
- •Main problem: restricted motion
- •Patients may not be responsive to instructions
- Need following degrees of motion
 - 1. Vertical
 - 2. Horizontal
 - 3. Rotational



http://cache.daylife.com/imageserve/0bS97VJbYyfaB/610x.jpg

Design Constraints

- Height, angle and rotation
- •Distance from patient's eye
- •Resolution of movement
- •Loading (weight of machine 83 lbs)



- •Ergonomic interface with patient and technologist
- Animals and humans

Last Semester's Work



- Purchased cross slide table and casters
- Assembled angle iron base
 - •Bolts attached table to base
- Configured casters and front mounting pivot point
 - Caster attach to base for easy rotation



Goals for the Semester

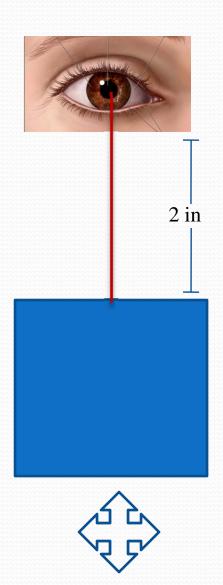


- Convert manual control to electronic control
 - Purchased three 1075 RPM motors
 - Attach motors to three axis joystick
- •Stabilize the device through rotation mechanism
 - Pivot point and worm drive to prevent unwanted rotation



Test the device in clinical setting

Testing



- •Current alignment time is 15 minutes
- Attach laser to camera
- •Develop target with similar size to retina
- •Record alignment times with manual and electronic system

Future Work

- Configure motors to work with cross slide table
- Develop rotation mechanism
- Consolidate controls to work with single joystick
- •Configure stop device to prevent excessive movement

Questions?