

Dynamic Beam Attenuator

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Clients:

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Advisor:

Dr. Paul Thompson

Background

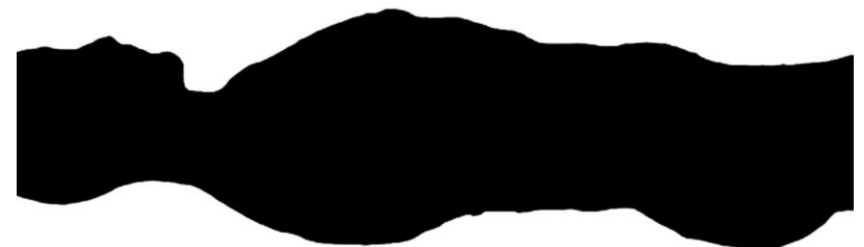
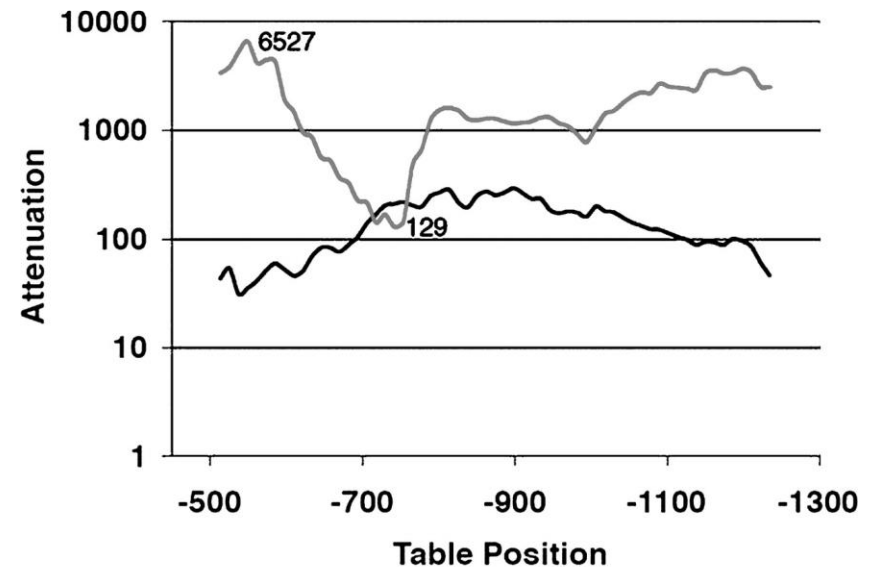
- Clients: Dr. Mistretta and Tim Szczykutowicz
- X-Ray Computed Tomography^{1,2} (CT)
 - X-Rays to image multiple planes in body
- Uses:
 - Diagnostic Imaging^{3,4}
 - CT-Guided Procedures⁵



C-arm CT⁶

Problem Definition

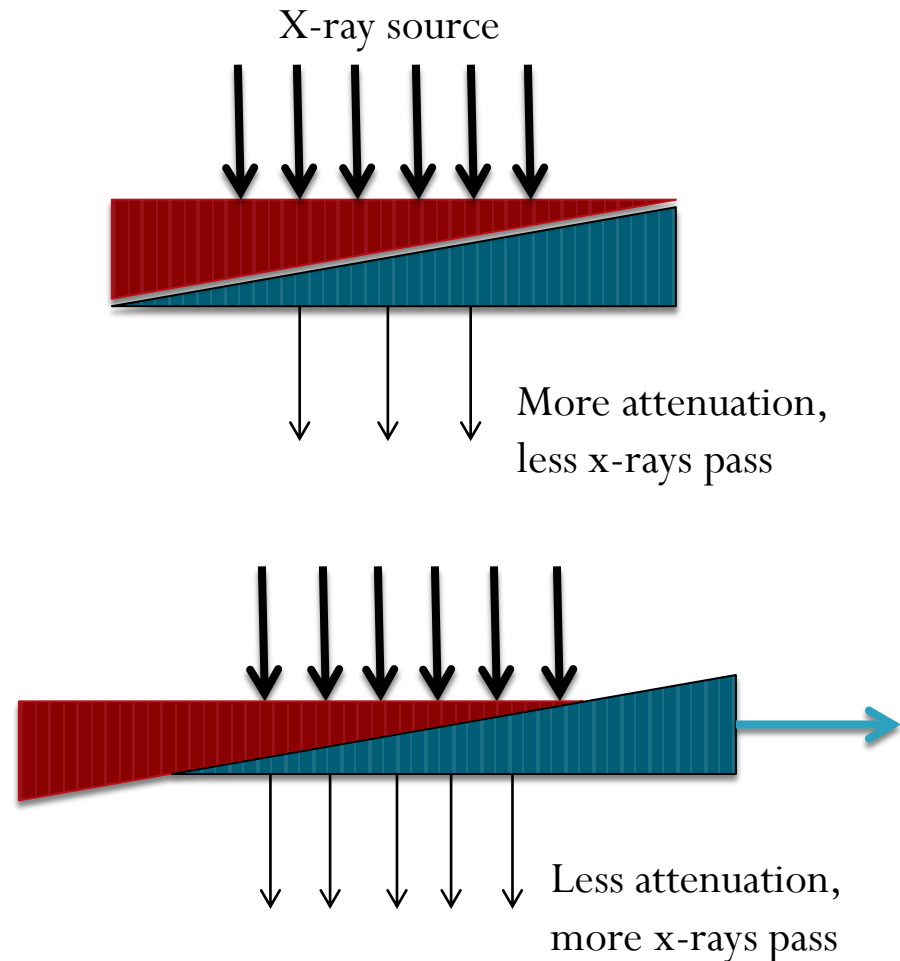
- Current CT scans lack dynamic dose modulation^{7,8}
 - High x-ray doses
 - Low quality images
- Competing devices:
 - Bowtie filters
 - kVp modulation
 - No dynamic filters



Attenuation heterogeneity across the body

Design Criteria

- Client Proposal: Attenuate X-Ray dosages⁷
 - Wedge thickness
 - Changes over time
 - Improve signal to noise uniformity
- Budget: ~\$5000
- Goal:
 - Proof of concept
 - Design new wedges with actuation



Current Prototype

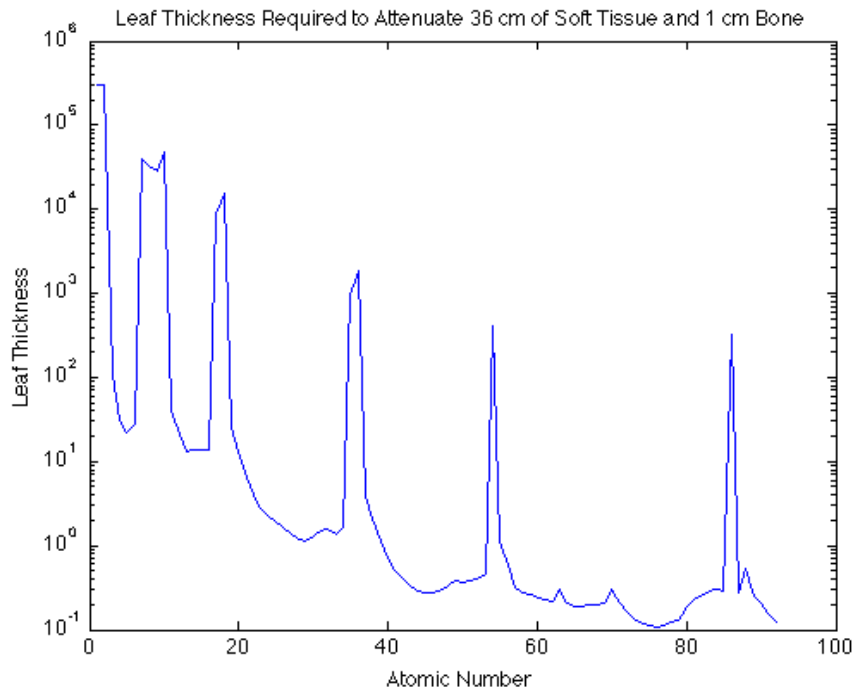
- 10 steel wedges
- Fixed wedge plate on the top
- Very heavy
- Cannot optimally attenuate
- One wedge attached to one motor



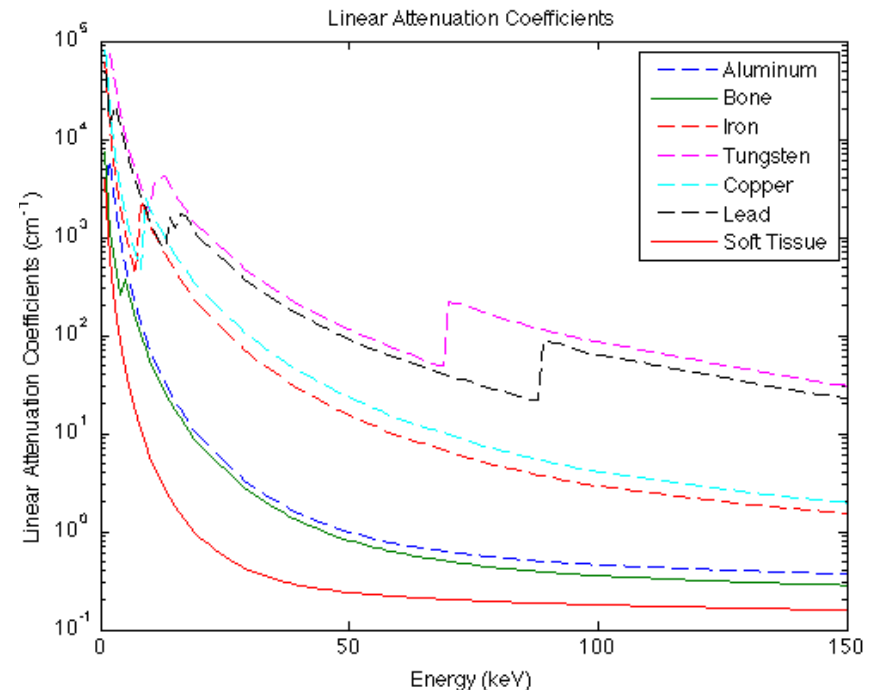
Current prototype with 10 steel wedges⁷

Material thickness & Beam Hardening

- Matlab simulations to model the wedge thickness required to attenuate 36 cm of soft tissue and 1 cm of bone
- Beam hardening: Energy change of x-rays as it passes through the material



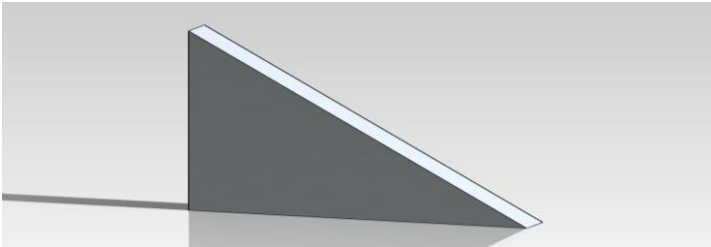
Thickness required for every element



Linear attenuation coefficients

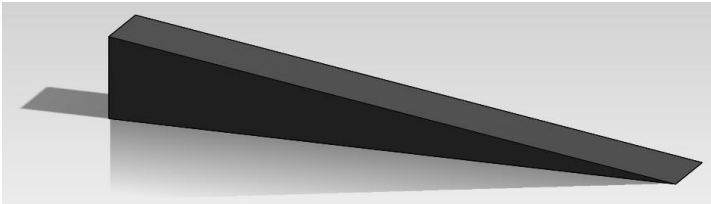
Wedge Material

Heel Thickness (mm)



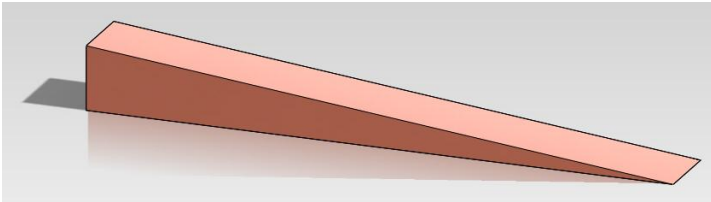
Aluminum

129.7



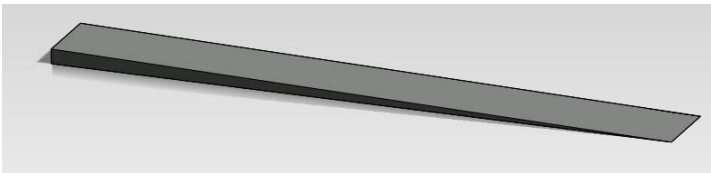
Iron

16.3



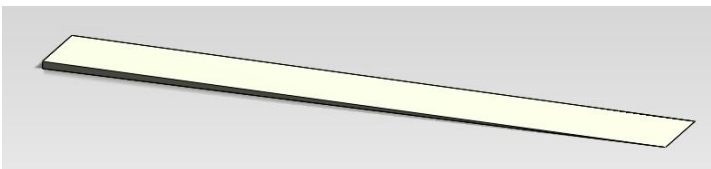
Copper

11.4



Lead

2.5



Tungsten

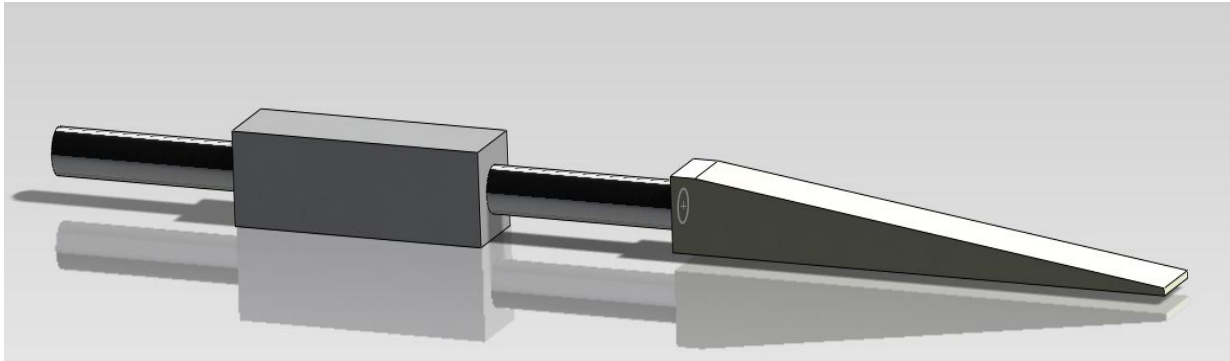
1.2

Materials Design Matrix

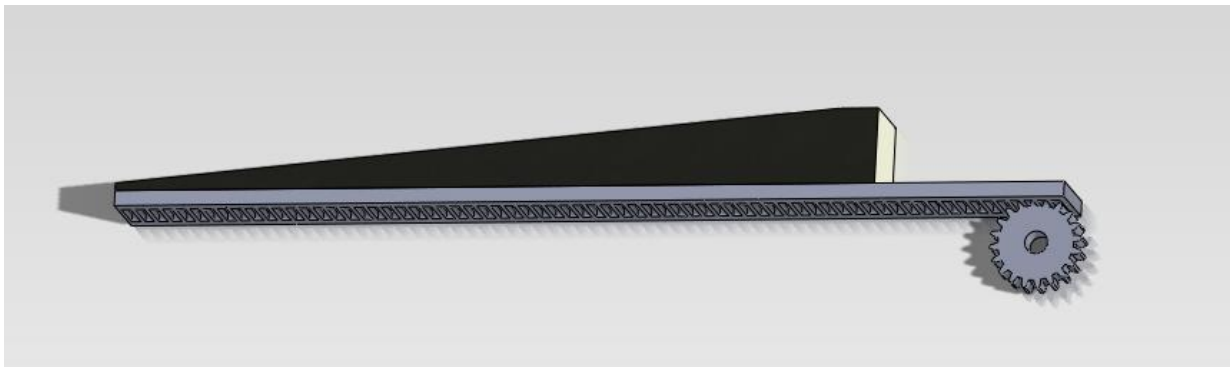
Criteria	Weight	Lead	Tungsten	Copper	Iron	Aluminum
Leaf Thickness	4	4.91	10	1.06	0.74	0.09
Beam Hardening	2.5	7.96	10	7.36	7.4	8.23
Machinability	2	6	2	6	8	10
Cost	1	2.33	0.10	1.36	4.27	10
Weight/Heaviness	0.5	8.33	10	2.27	1.80	0.66
Total (out of 100)		58.0	74.1	37.1	42.6	51.3

Note: Values quantitatively determined and normalized to a scale from 1 to 10. Each criteria was weighted so that the grand total was from 1 to 100.

Wedge Actuation



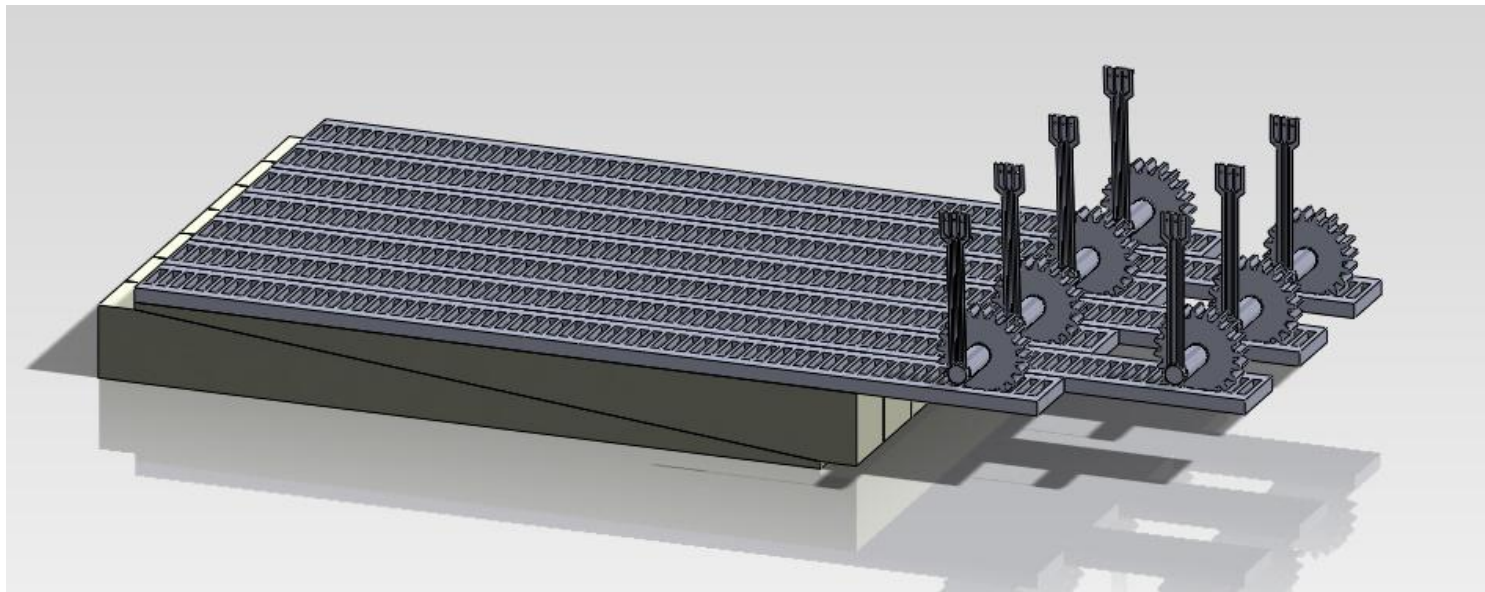
Wedge with linear actuator



Wedge with rack and pinion

Preliminary Design

- Tungsten wedges with rack and pinion actuation in flush configuration
- Motors placed on same side with alternating positions
- Actuation and configuration may not be the final design



**Proposed design based on size restraints
(Wedge thickness not drawn to scale)**

Future Work

- Machine wedges and housing
- Select, purchase, and implement actuation mechanism
- Assemble entire device
- Program the device
- Test with phantoms

Acknowledgements

- Clients: Chuck Mistretta and Tim Szczykutowicz
- Advisor: Dr. Paul Thompson
- Siemens engineer: Kevin Royalty
- Erick Oberstar

References

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